

**McCormick**



Northwestern Engineering

**Northwestern University Transportation Center**

# **DEVELOPMENT, CALIBRATION AND APPLICATION OF SIMULATION-BASED DYNAMIC TRAFFIC ASSIGNMENT TO GREATER CHICAGO NETWORK USING DYNASMART-P**

Ali Zockaie K.

Meead Saberi

Hani S. Mahmassani

March 7, 2012

**Northwestern University**



# Outline

- Introduction to Simulation-based DTA
- Greater Chicago Network
- Calibration and Validation of DYNASMART-P
  - Supply side
  - Demand side
- Applications
  - Weather-responsive traffic estimation and prediction
  - Congestion management

# Introduction to Simulation-based DTA

## DYNASMART-P

What is DYNASMART-P?

- **DY**ynamic **N**etwork **A**ssignment-**S**imulation **M**odel for **A**dvanced **R**oadway **T**elematics (**P**lanning version)
- It is an intelligent transportation network design, planning, evaluation, and traffic simulation tool.

## State of Practice in Network Modeling

- Most agencies use static assignment models, often lacking formal equilibration, with very limited behavioral sensitivity to congestion-related phenomena (incl. reliability)
- Some agencies use traffic micro-simulation models downstream from assignment model output, primarily for local impact assessment
- Time-dependent (dynamic) assignment models continuing to break out of University research into actual application— market growing, still fragmented, with competing claims and absence of standards:
  - existing static players adding dynamic simulation-based capabilities,
  - existing traffic micro-simulation tools adding assignment (route choice) capability, often in conjunction with meso-simulation
  - standalone simulation-based DTA tools

## State of Practice in Network Modeling

- Applications to date complementary, not substitutes, for static assignment; primary applications for operational planning purposes: work zones, evacuation, ITS deployment, HOT lanes, network resilience, etc...
- Existing commercial software differs widely in capabilities, reliability and features; not well tested.
- Equilibration for dynamic models not well understood, and often not performed
- Dominant features, first introduced by DYNASMART-P in mid 90' s:
  - Micro-assignment of travelers; ability to apply disaggregate demand models
  - Meso-simulation for traffic flow propagation: move individual entities, but according to traffic flow relations among averages (macroscopic speed-density relations): faster execution, easier calibration
  - Ability to load trip chains (first tool with this capability, essential to integrate with activity-based models)

# Greater Chicago Network

# Data Overview

- Five categories of data required for DYNASMART-P
  - Network data
  - Control data
  - Demand data
  - Scenario data
  - System data

First three groups are critical for setting up the network

Last two group are critical for scenario analysis



## Sources of data

### ➤ Network:

CMAP TransCAD network

converted to DYNASMART-P using DYNASMART-P utility (DynaBuilder)

### ➤ Control:

Signal locations based on TranCAD network

Other control locations inferred by spatial reasoning logic, confirmed by Google Earth

Timing plans have been coded in DSPEd

- Actual timing plans not available
- Actuated Control signal timing plans specified by default

### ➤ Transit:

Bus routes and frequencies

- Not implemented to this network, yet

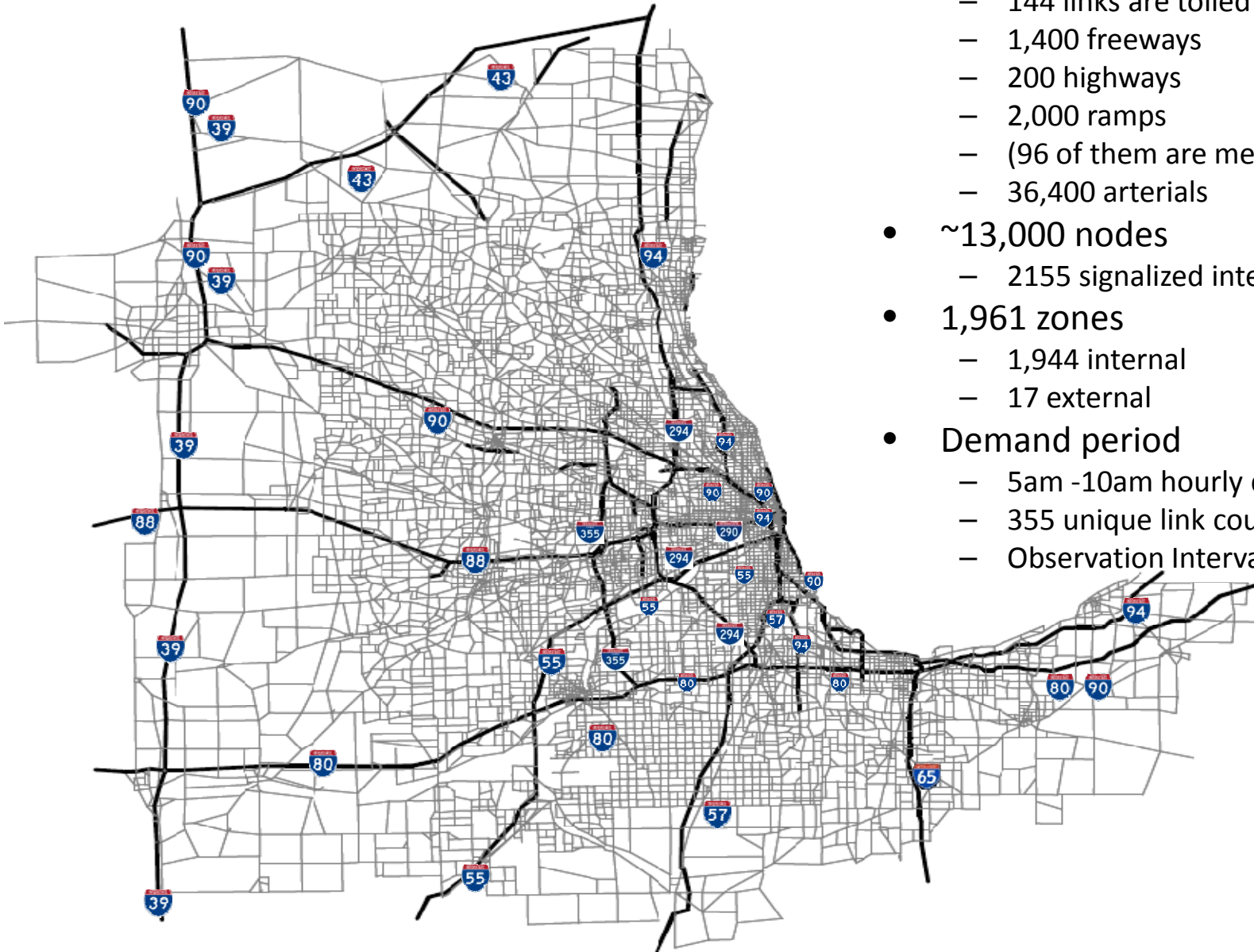
### ➤ Demand:

Static demand matrix provided on daily basis and hourly factors

Link counts obtained from IDOT loop detectors (in 5 minutes intervals)

# Greater Chicago Network

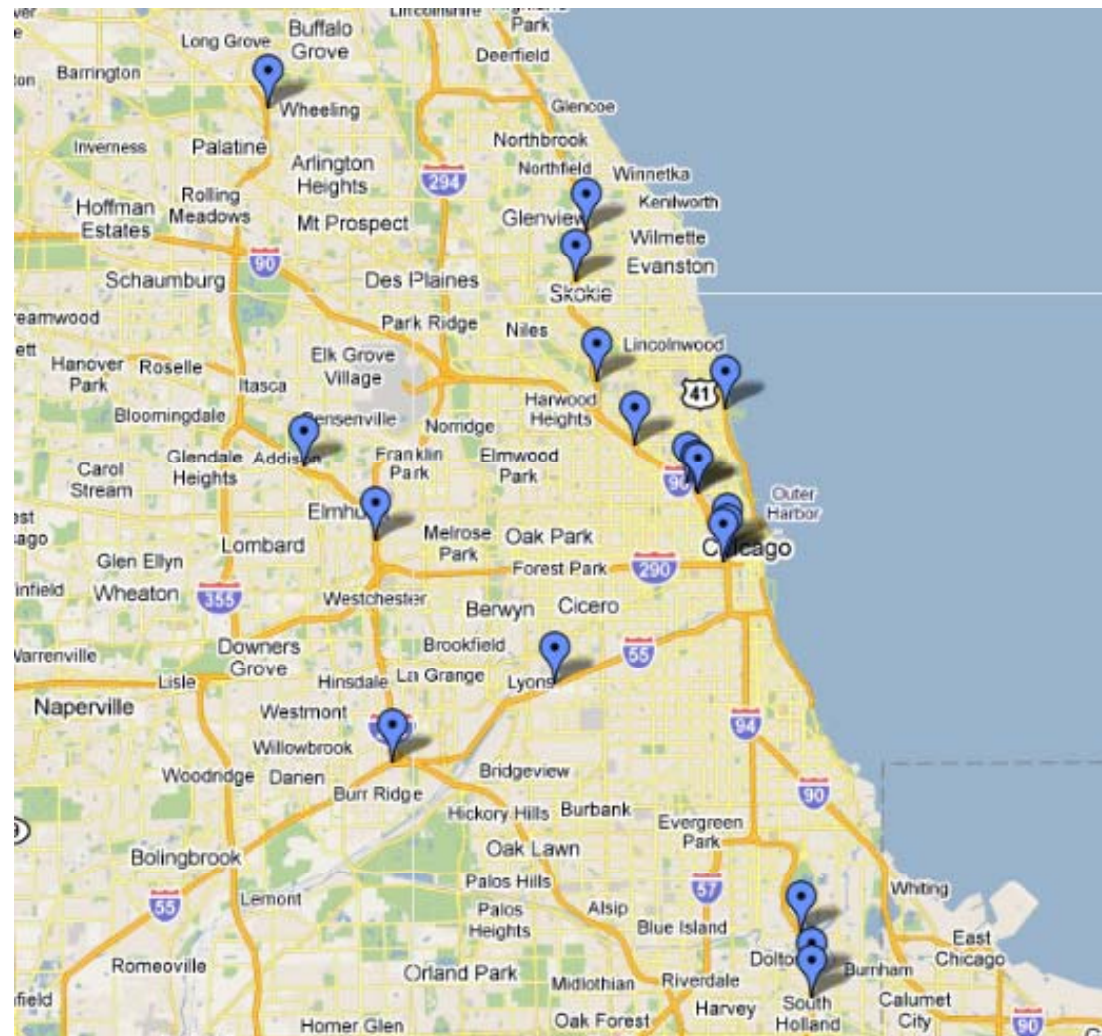
- ~40,000 links
  - 144 links are tolled
  - 1,400 freeways
  - 200 highways
  - 2,000 ramps
  - (96 of them are metered)
  - 36,400 arterials
- ~13,000 nodes
  - 2155 signalized intersections
- 1,961 zones
  - 1,944 internal
  - 17 external
- Demand period
  - 5am -10am hourly demand
  - 355 unique link counts
  - Observation Interval: 5 min



# Calibration and Validation of DYNASMART-P

# Calibration and Validation of DYNASMART-P I- Supply side

## Location of traffic data for traffic flow calibration



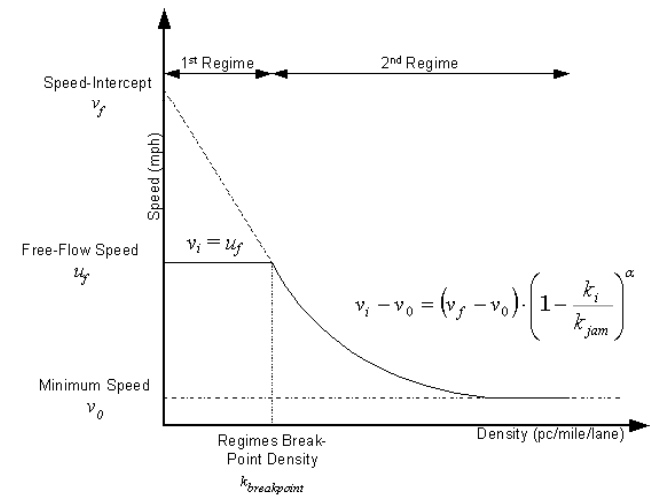
## Calibrating parameters in the traffic flow model / Procedure

**Step 1.** Plot the speed vs. density graph, and set initial values for all the parameters, i.e. breakpoint density ( $k_{bp}$ ), speed-intercept ( $v_f$ ), minimum speed ( $v_0$ ), jam density ( $k_{jam}$ ), and the shape parameter ( $\alpha$ ), based on observations.

**Step 2.** For each observed density ( $k_i$ ), calculate the predicted speed value and the parameters initialized in Step 1.

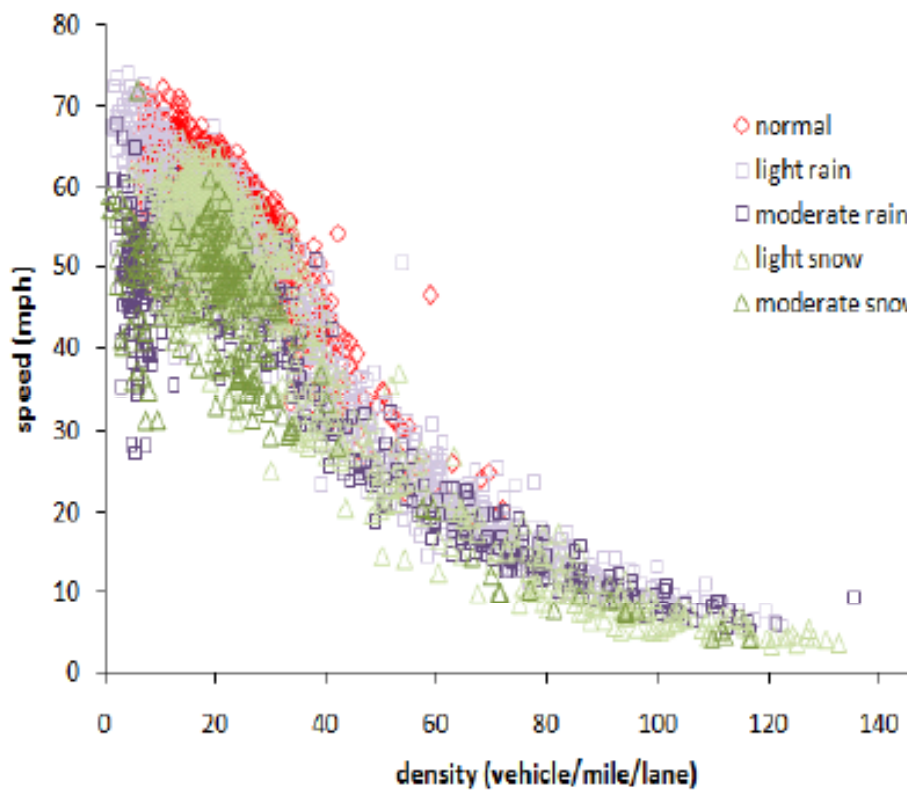
**Step 3.** Compute the squared difference between observed speed value ( $v_i$ ) and predicted speed value, for each data point, and sum the squared error over the entire data set.

**Step 4.** Minimize the sum of squared error obtained in Step 3, by changing the values of model parameters.

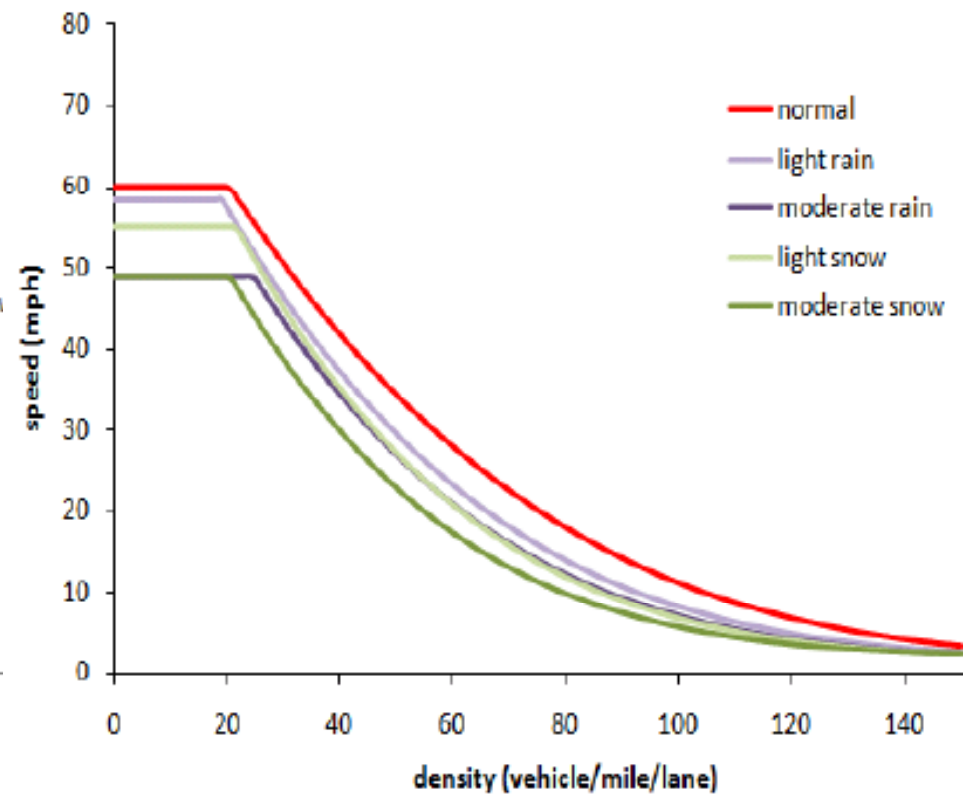


**Modified Greenshields**

## Calibrating parameters in the traffic flow model for different weather conditions



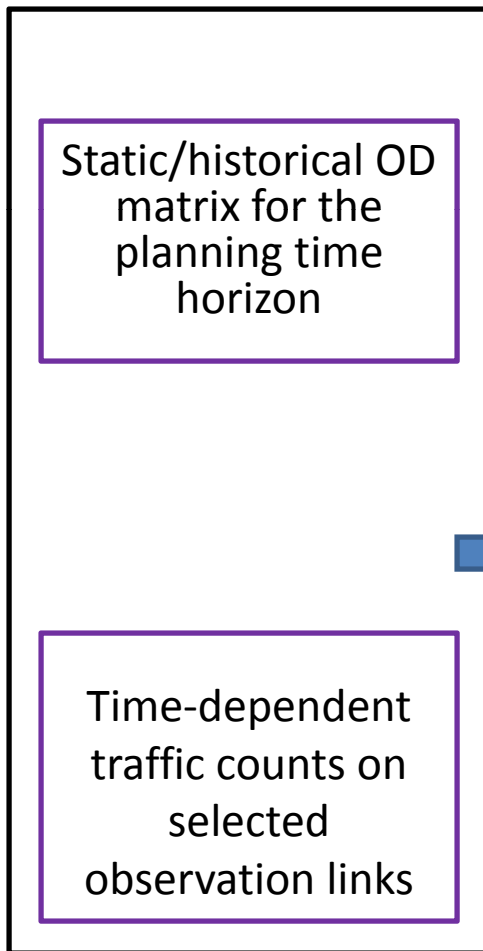
Speed-Density Data



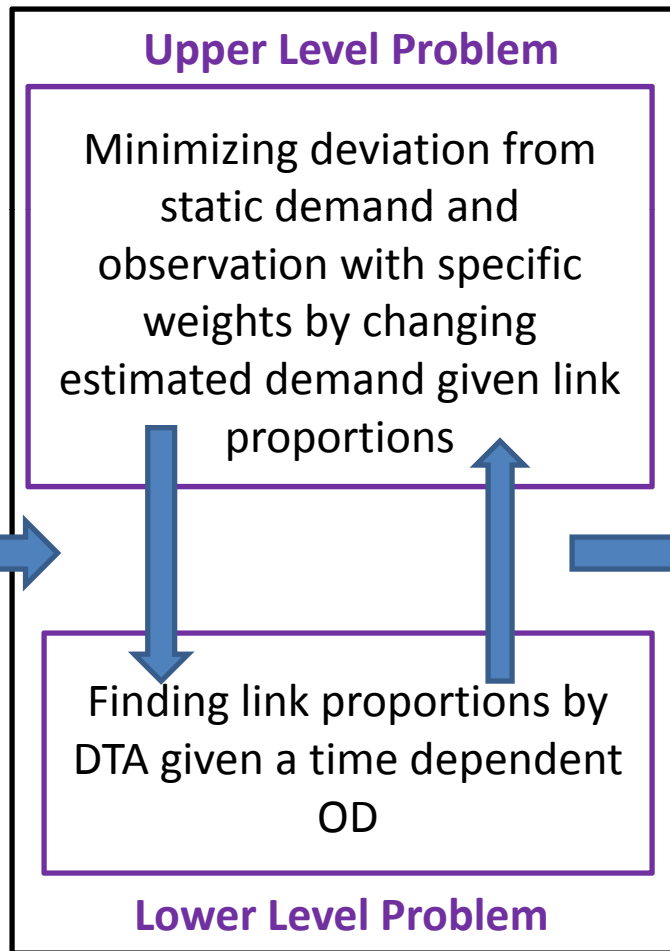
Speed-Density Calibrated Relationship

# Time-dependent OD Estimation / Methodology

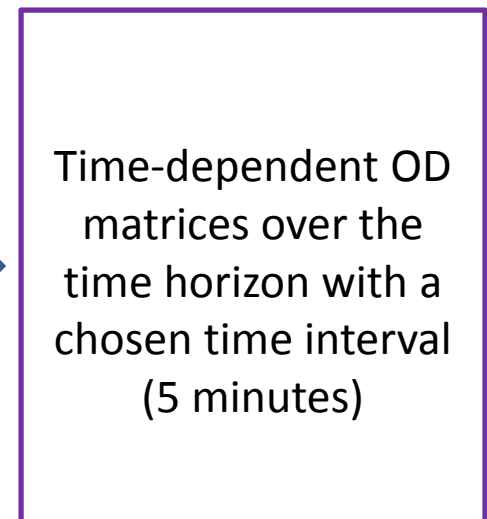
## Input



## Bi-level Optimization



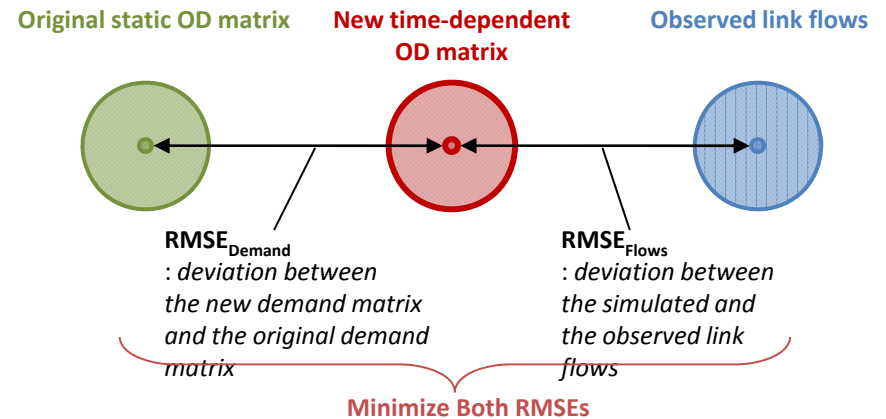
## output



## Time-dependent OD Estimation for large scale networks / Results

$$RMSE_{Demand} = \sqrt{\frac{\sum_{i=1}^I \sum_{j=1}^J \left[ \left\{ \sum_{h=1}^H d_{i,j,h} \right\} - \delta_{i,j} \right]^2}{IJH - 1}}$$

$$RMSE_{Flows} = \sqrt{\frac{\sum_{l=1}^L \sum_{t=1}^T [M_{l,t} - O_{l,t}]^2}{LT - 1}}$$



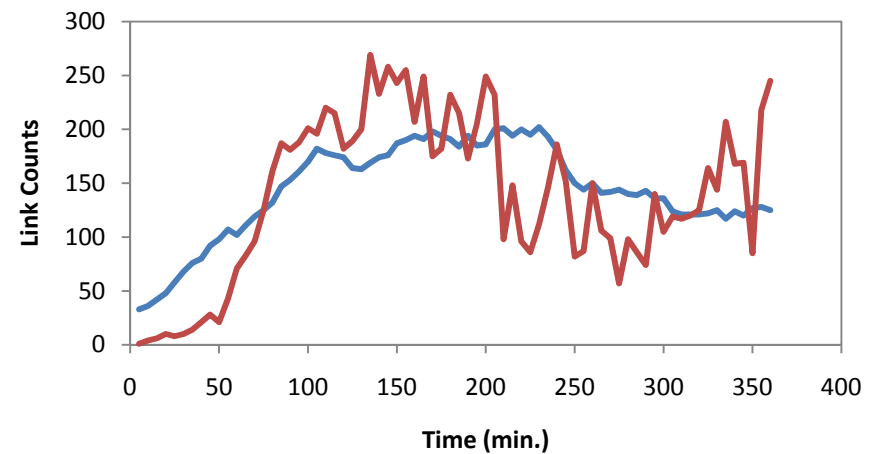
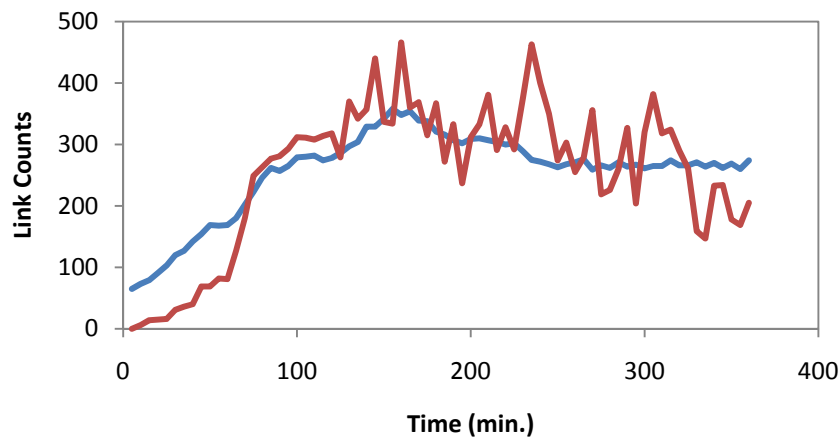
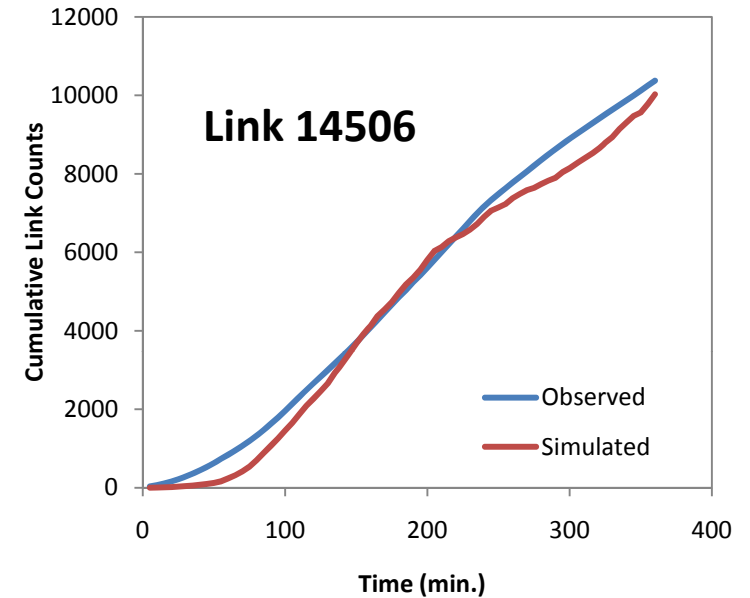
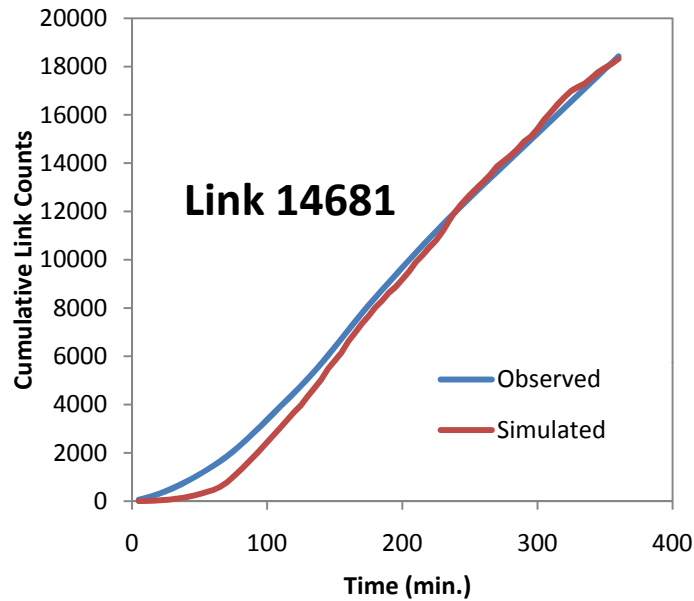
	Number of Trips	RMSE Values	
	SOV*	$RMSE_{Demand}$	$RMSE_{Flows}$
Historical OD matrix	4,145,413	0**	228.759
New time-dependent OD matrix after <b>Iteration 1</b>	4,179,062	0.044	219.148
New time-dependent OD matrix after <b>Iteration 2</b>	4,157,199	0.049	217.739
New time-dependent OD matrix after <b>Iteration 3</b>	4,141,043	0.049	217.030

\* SOV: Single-occupancy vehicle

\*\* Deviation is zero because  $RMSE_{Demand}$  in this case represents the deviation between the static OD matrix and itself.



## Time-dependent OD Estimation / Results



## VALIDATION OF WEATHER SENSITIVE DYNASmart-P

$$RMSE_{Speeds} = \sqrt{\frac{\sum_{l=1}^L \sum_{t=1}^T [MS_{l,t} - OS_{l,t}]^2}{LT - 1}}$$

$$RMSE_{Flows} = \sqrt{\frac{\sum_{l=1}^L \sum_{t=1}^T [M_{l,t} - O_{l,t}]^2}{LT - 1}}$$

SNOW Scenario: 2010-01-07 (Chicago)			
RMSE Speeds		RMSE Flows	
With Weather Features	Without Weather Features	With Weather Features	Without Weather Features
26.2731	36.0101	181.5455	173.1032

Relative difference : 37%

Relative difference : -5%

# Applications

I- Weather-responsive traffic estimation and prediction

# Objectives

- Reduce the impact of **inclement weather events** and mitigate **congestion**
- Determine weather-related advisory and controls based on predicted traffic conditions and anticipatory road weather information
- This calls for integrated real-time **Weather-Responsive Traffic Management** (WRTM) and a **Traffic Estimation and Prediction System** (TrEPS)

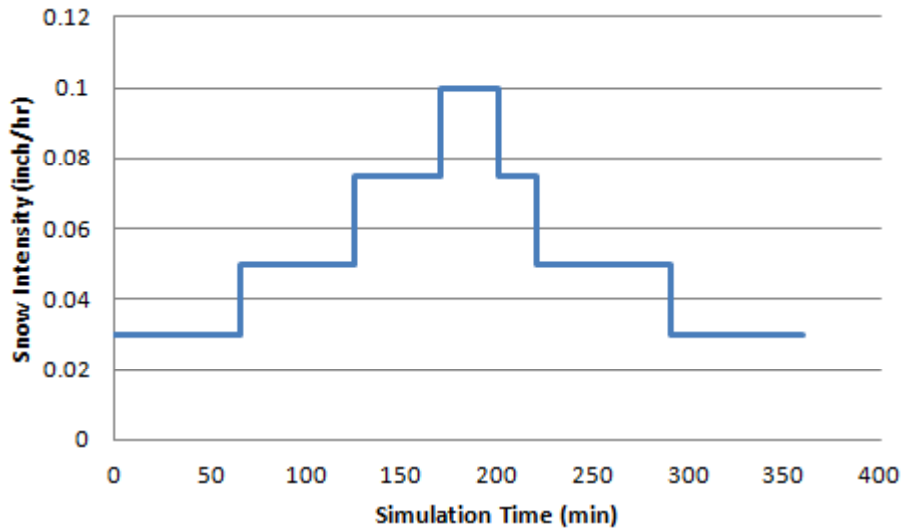
## Offline WRTM

- Historical weather and traffic count data from different days can be used to simulate **various real-world scenarios**.
- Many different **What-If scenarios** can be tested and evaluated.
- Successful scenarios can be added to the **WRTM strategy repository** to be used as an **initial input** for real-time implementation in DYNASMART-X via **Scenario Manager**.

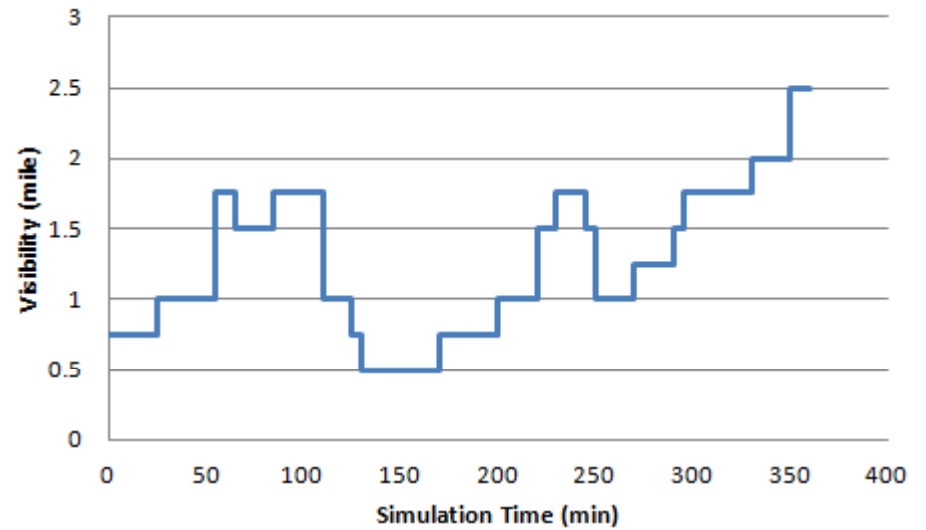
## Description of 5 Scenarios

1. **Clear Day:** Maximum visibility with zero precipitation.
2. **Snow:** Visibility ranges from 0.5 to 2.0 miles, snow intensity ranges from 0.03 to 0.10 inches per hour, network-wide.
3. **Snow with VMS – Variable Speed Limit:** Speed reduction strategies are implemented on freeway corridors.
4. **Snow with VMS – Detour:** Vehicles are detoured from some heavily impacted links to alternative routes.
5. **Snow with VMS – Detour plus Variable Speed Limit:** Vehicles are detoured from some heavily impacted links to alternative routes and Speed reduction strategies are implemented on freeway corridors.

# Weather data during simulation with snow



Snow Intensity

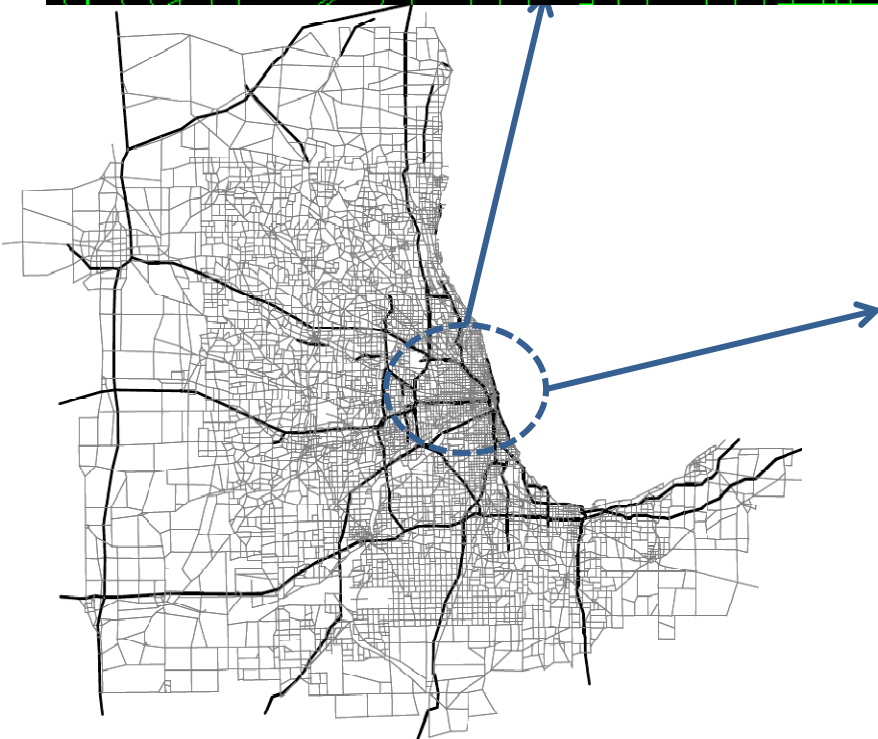
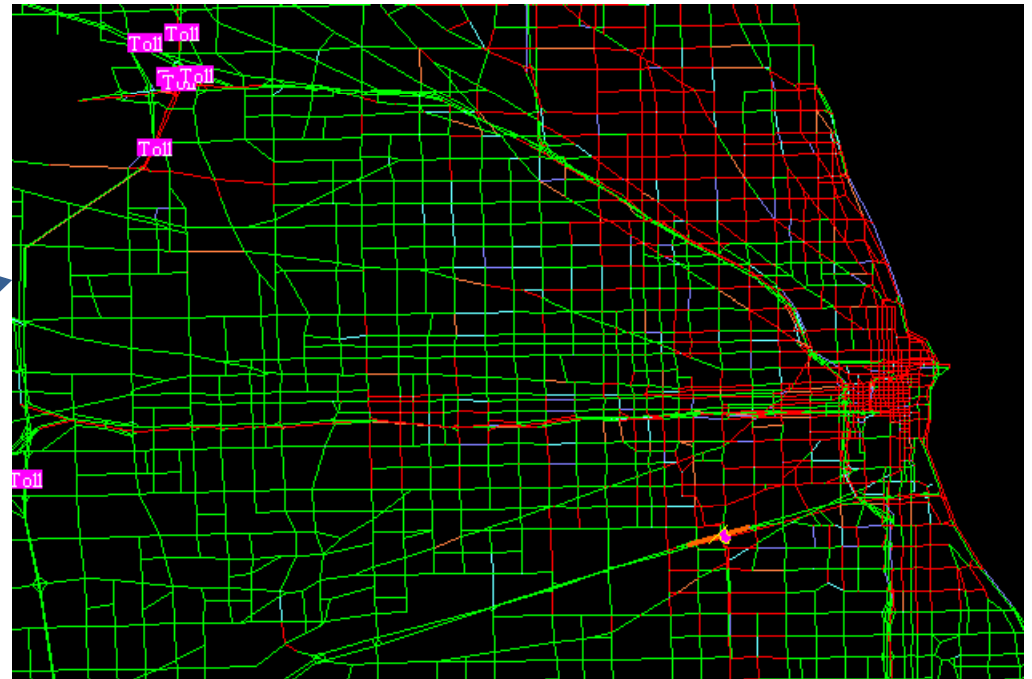
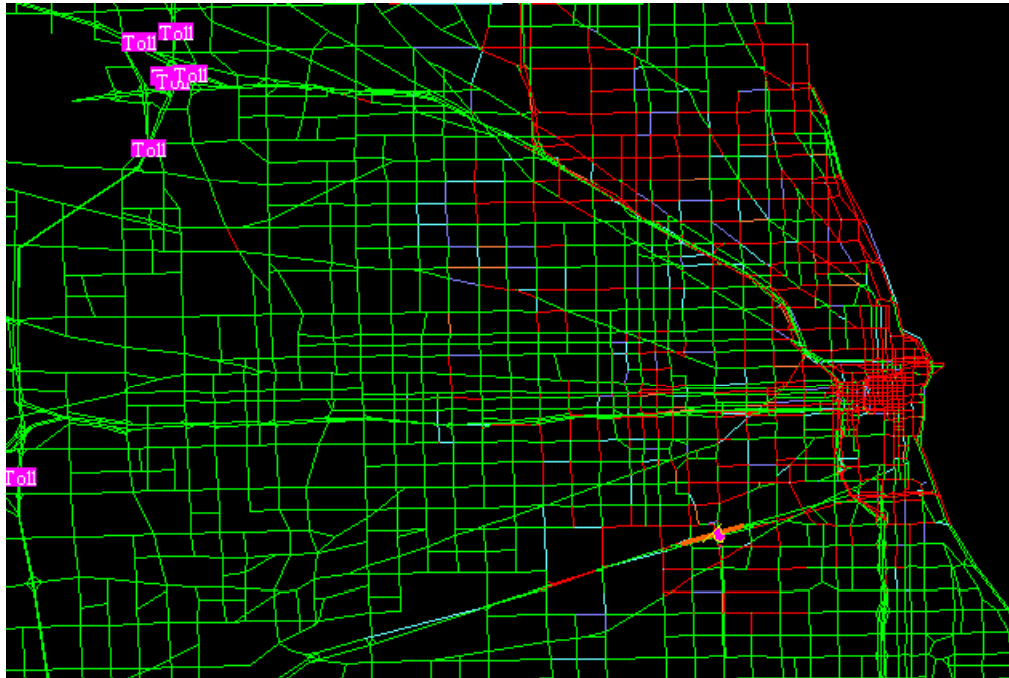
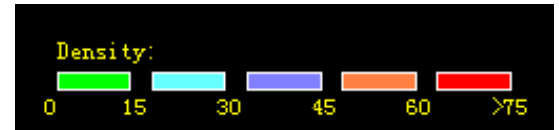


Visibility

# Weather Impact on density

Clear Day

Snow





# Lake Shore Dr North bound between Belmont and Fullerton

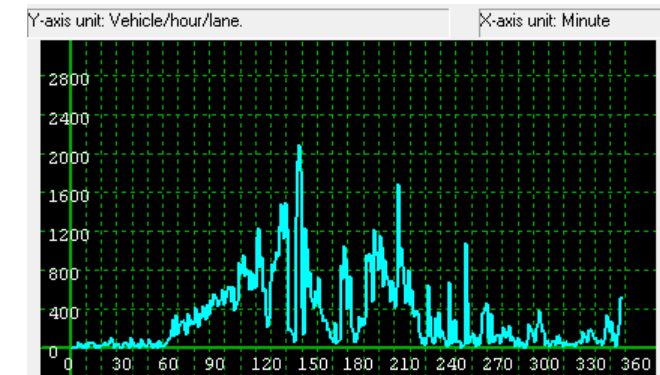
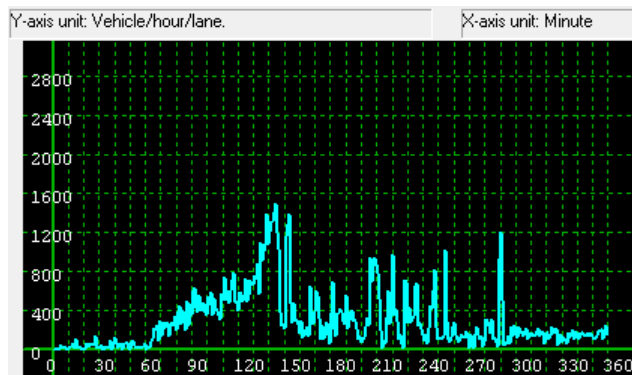
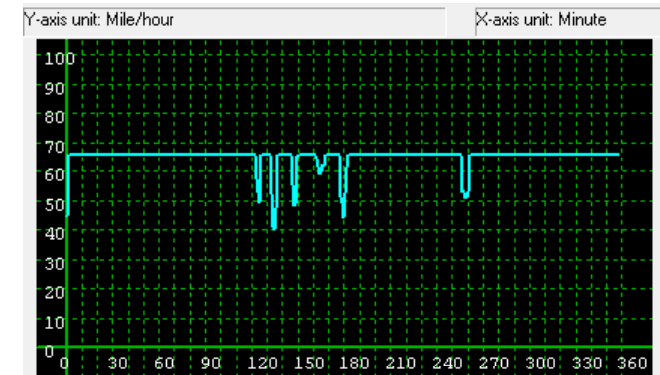
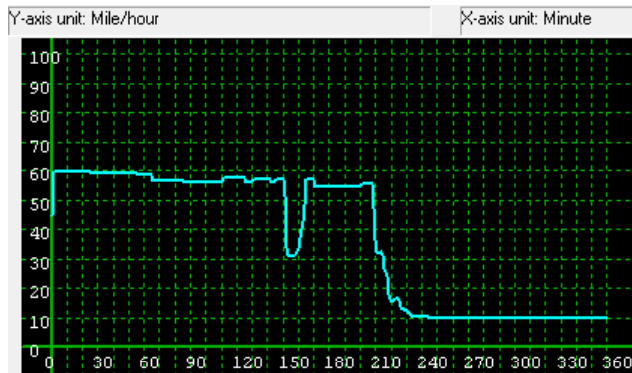
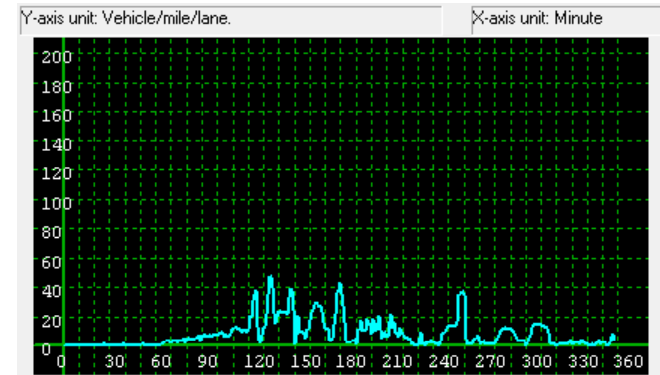
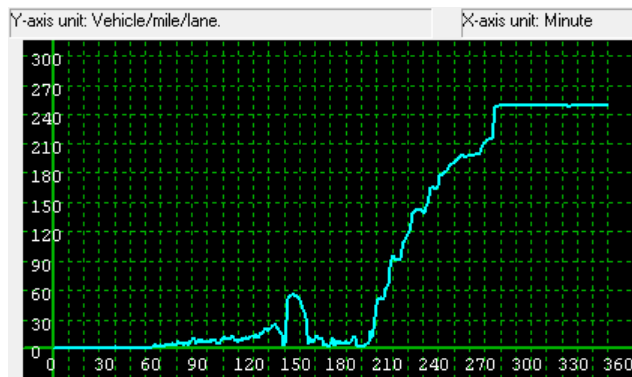
Clear Day

Snow

Density

Speed

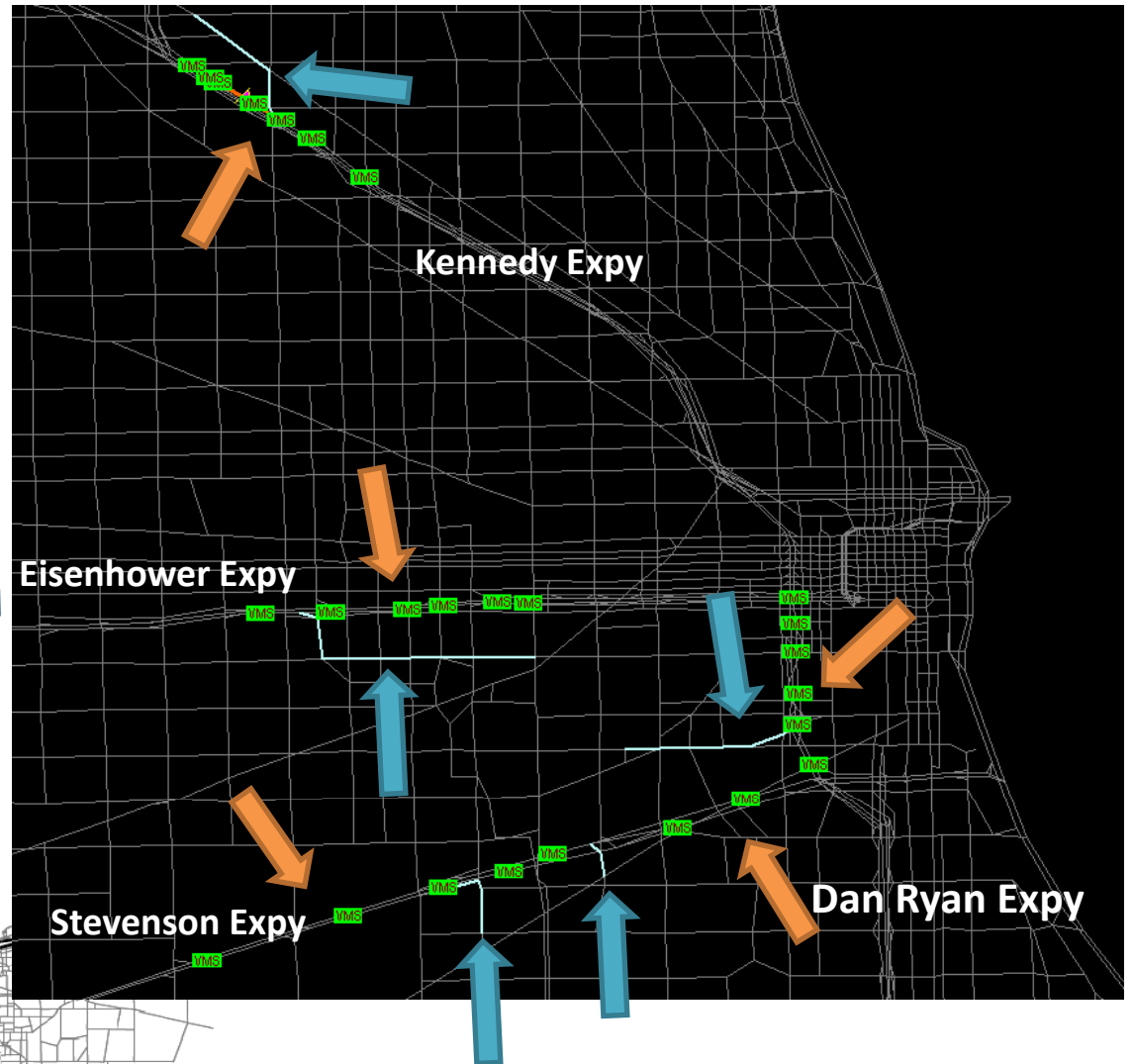
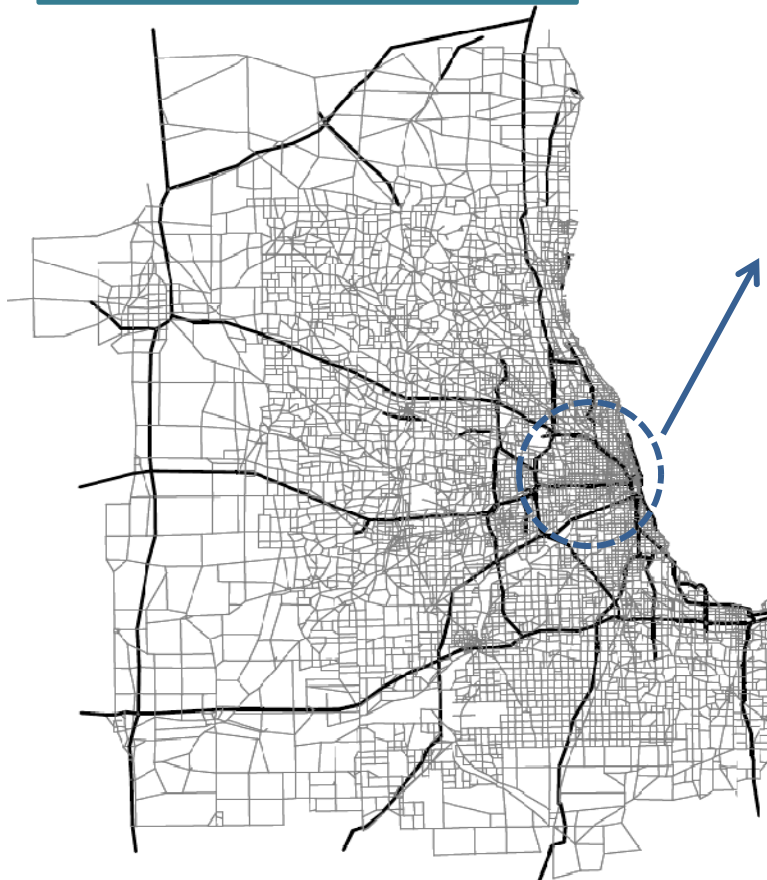
Volume

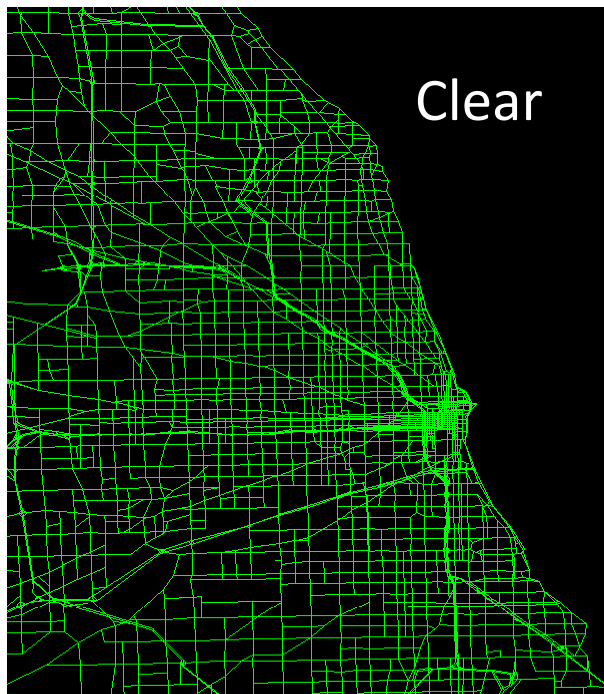


# WRTM Strategies

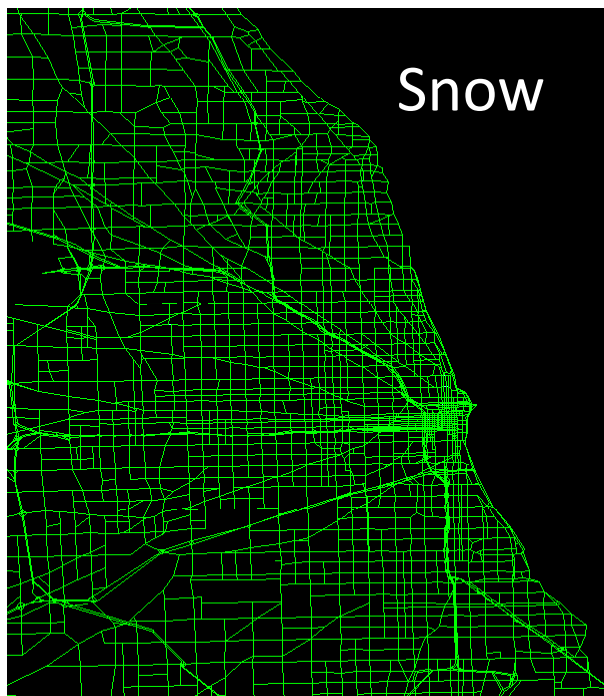
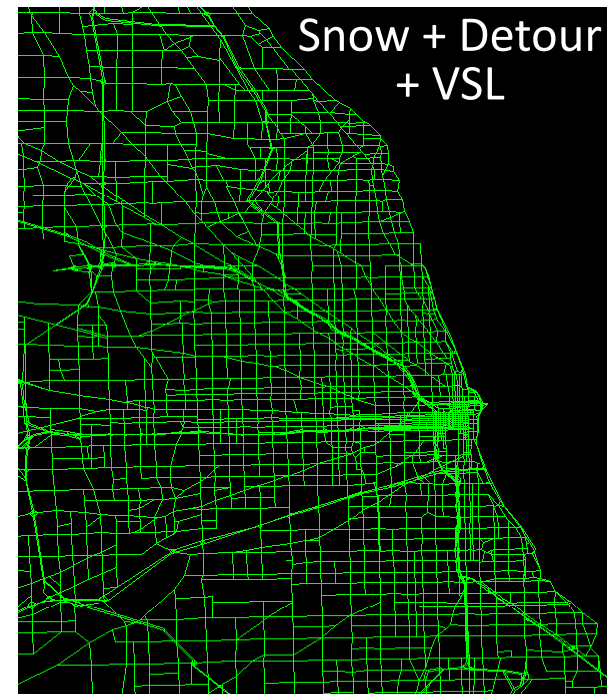
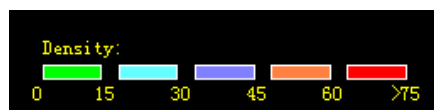
VMS - VSL

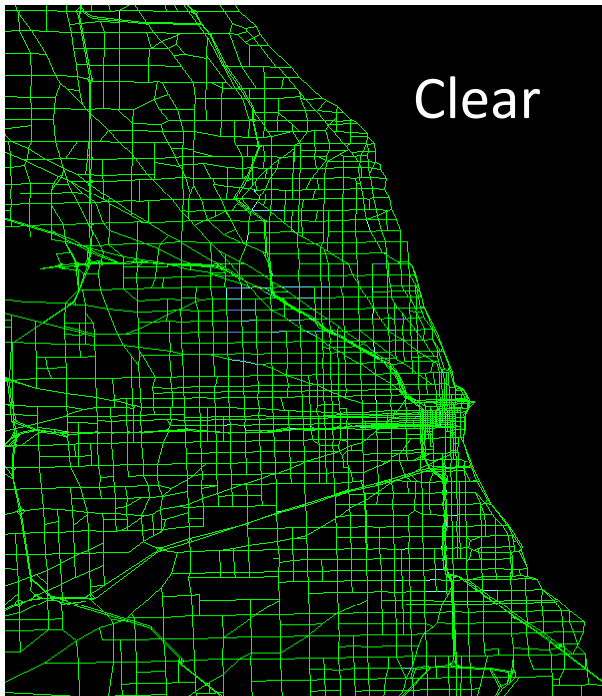
VMS - Detour



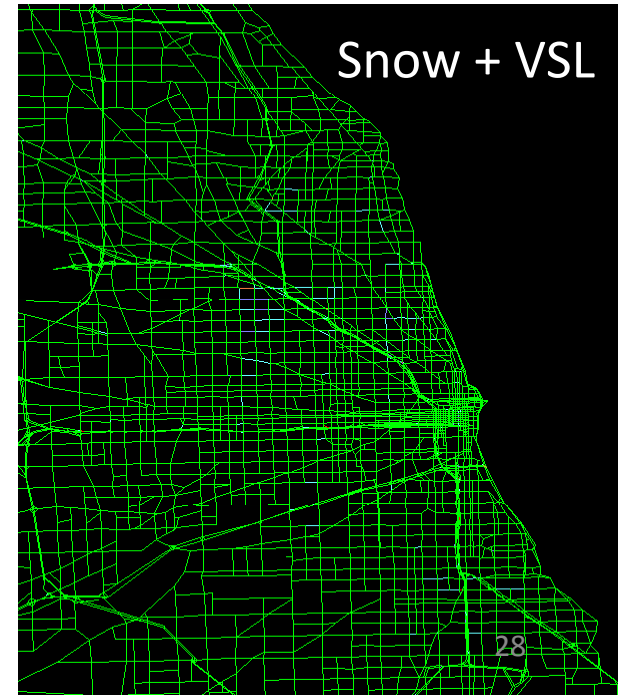
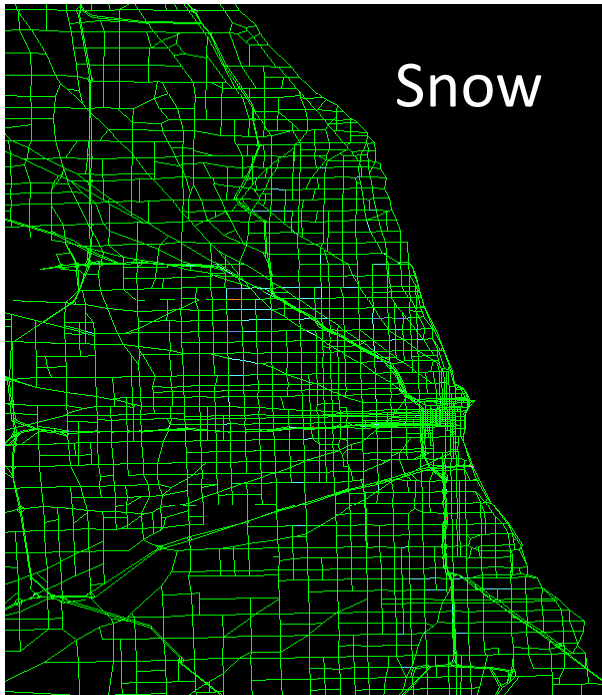
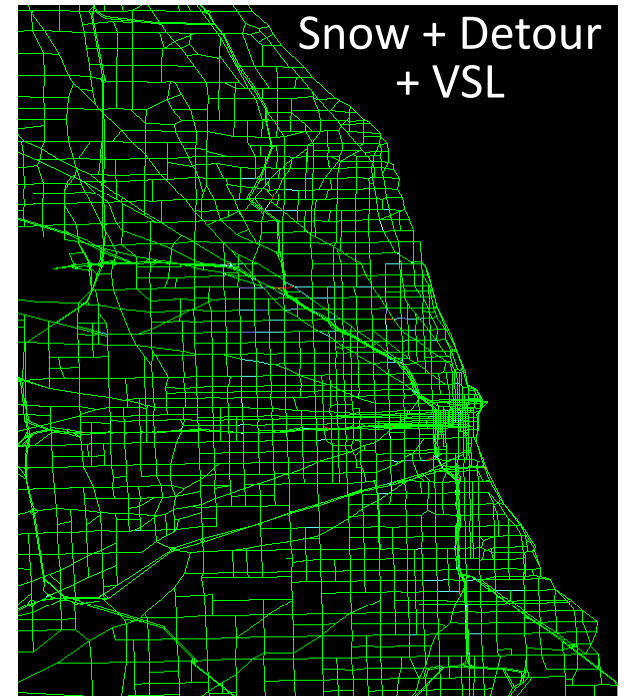
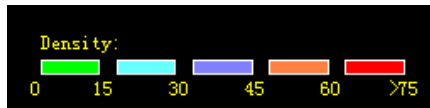


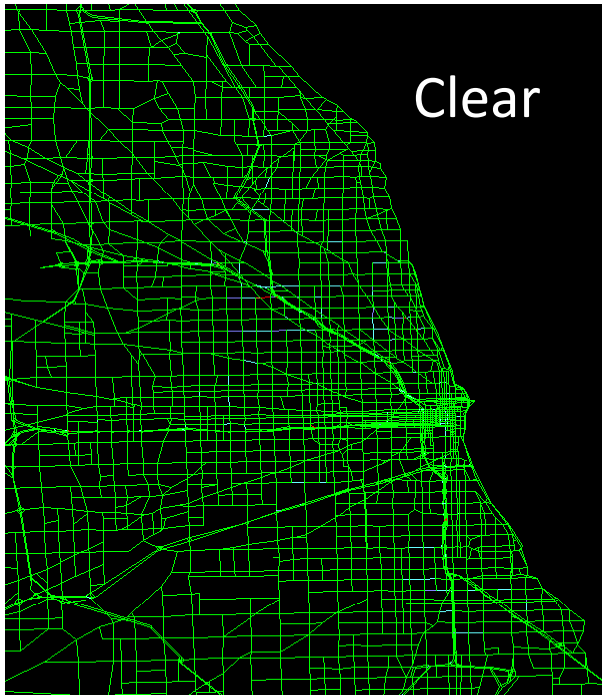
5:00 am  
Density



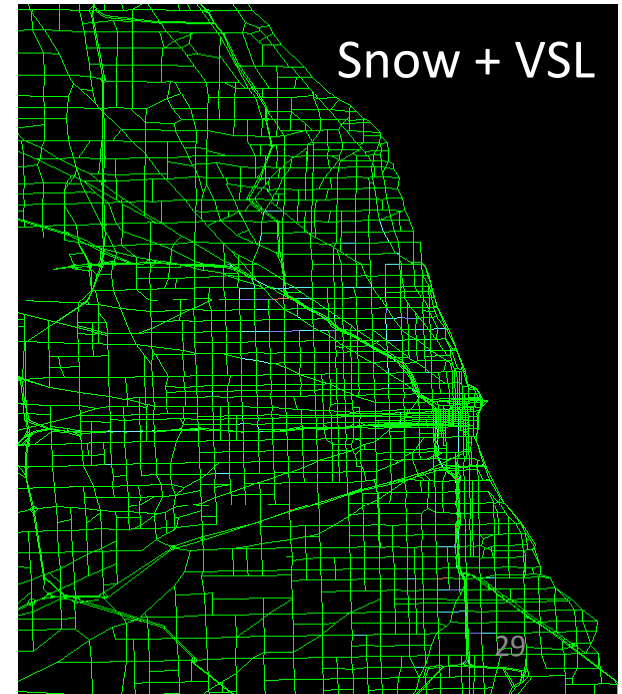
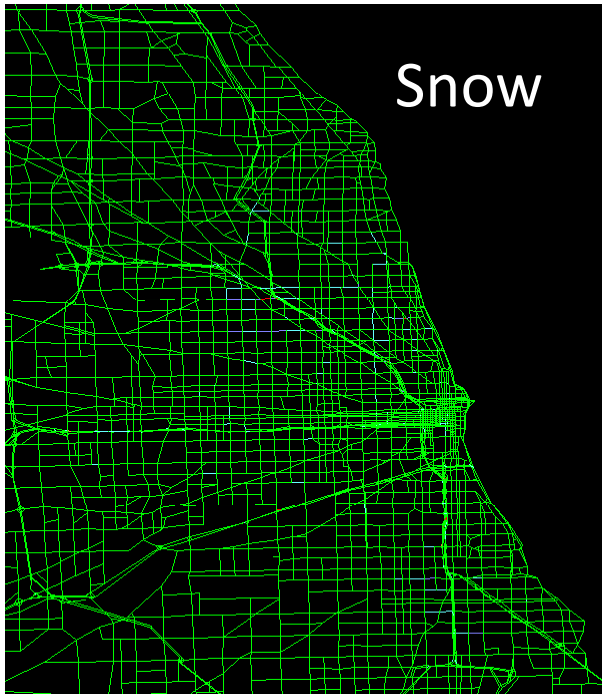
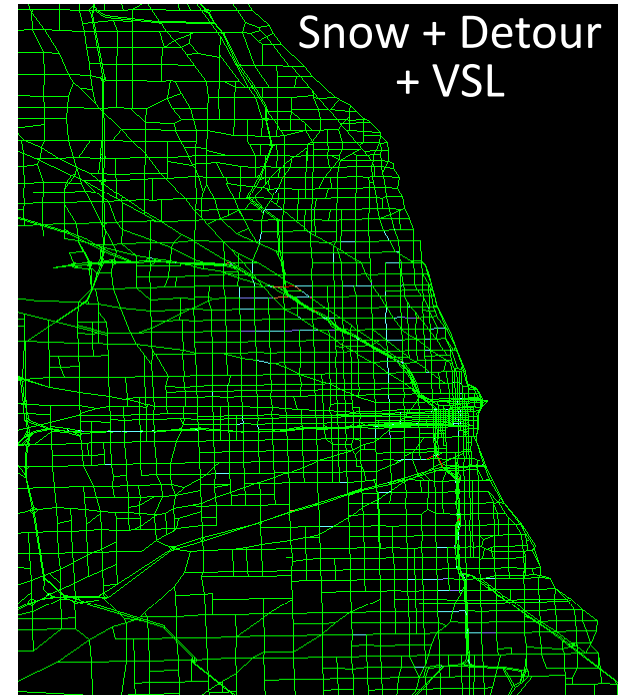
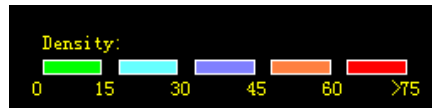


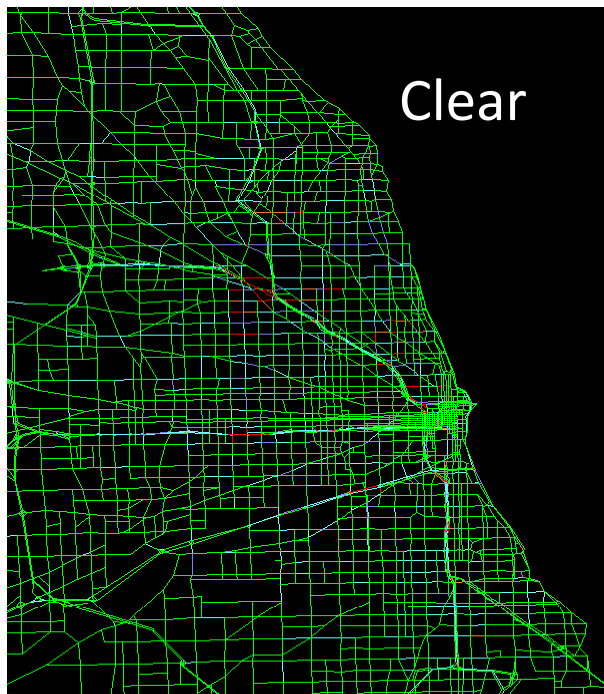
5:30 am  
Density



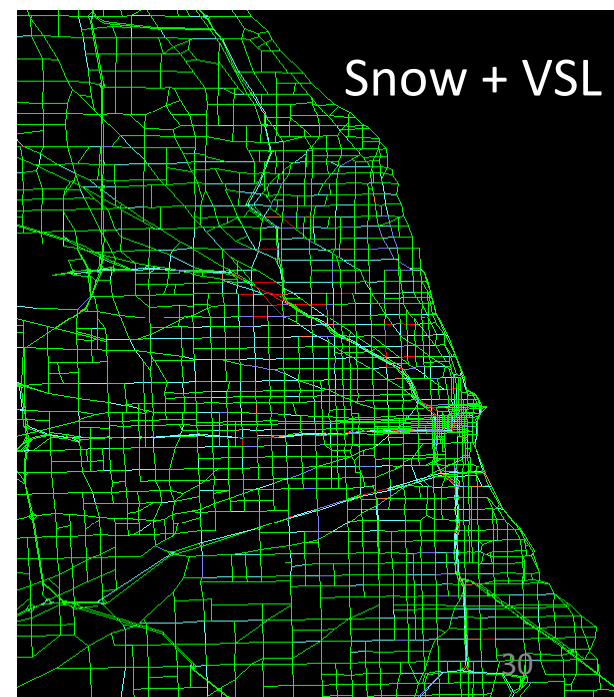
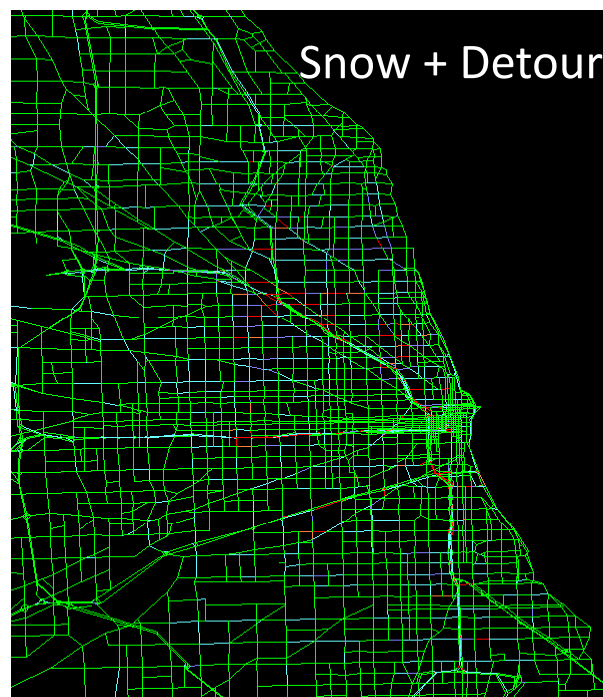
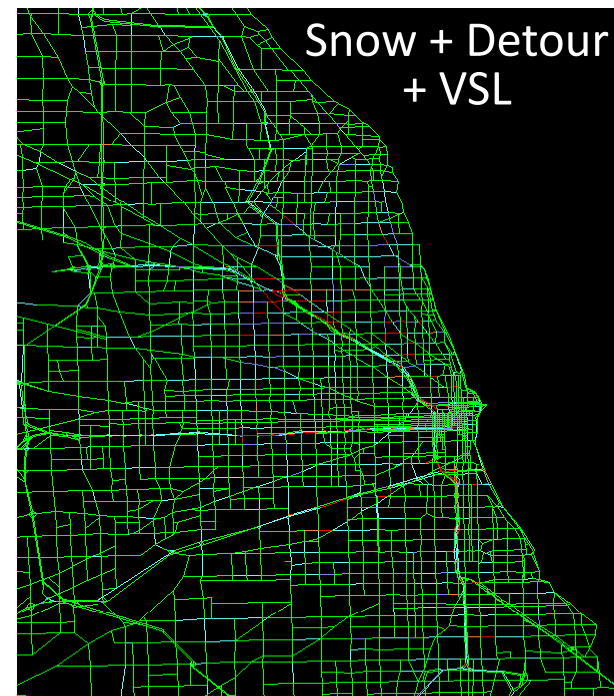
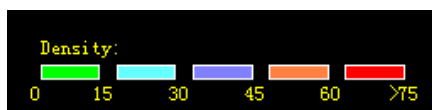


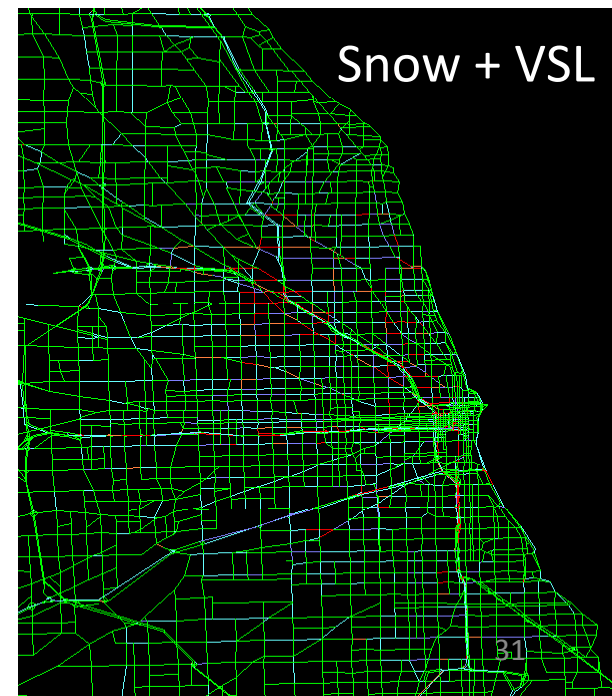
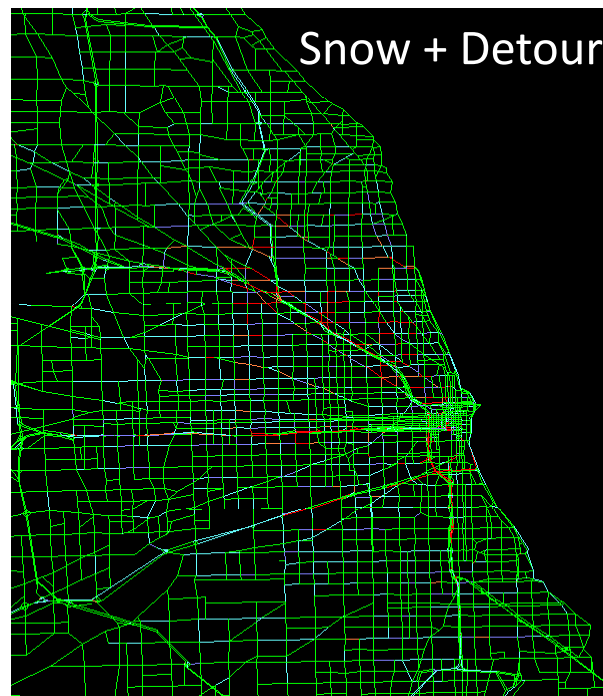
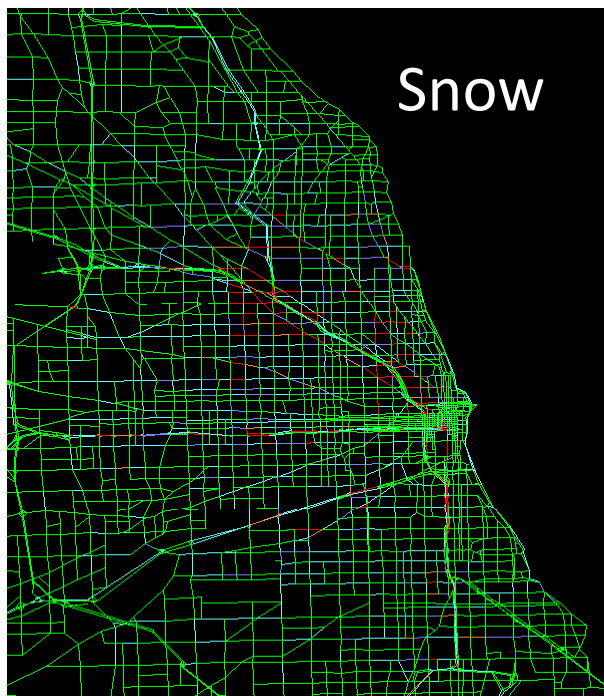
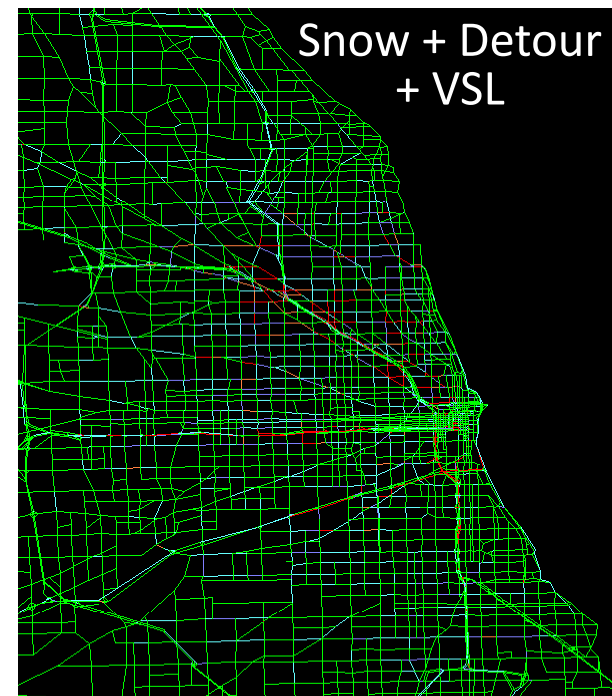
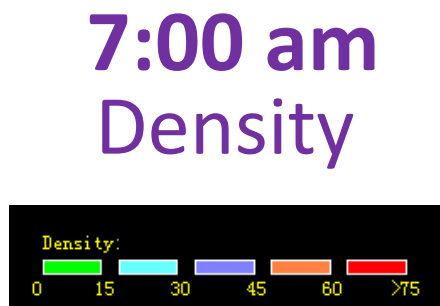
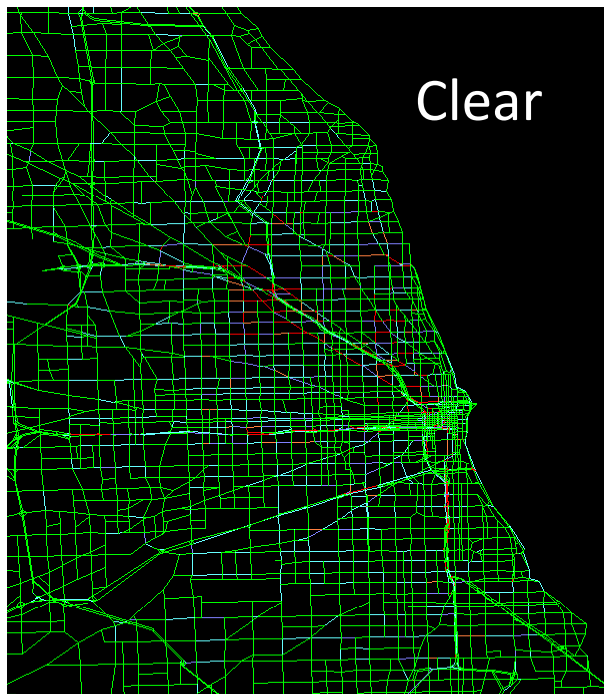
6:00 am  
Density

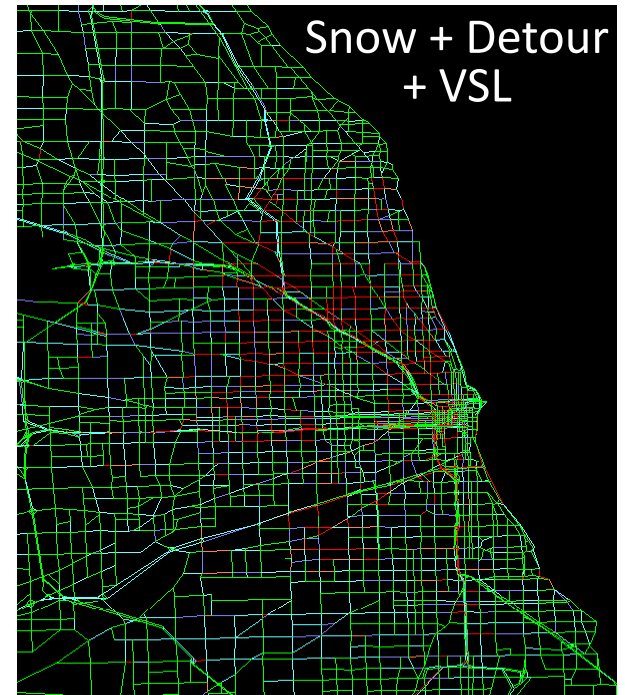
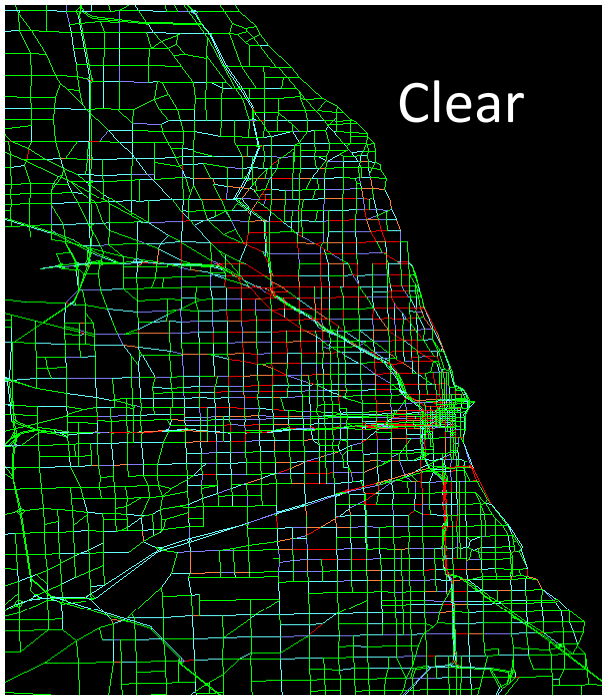




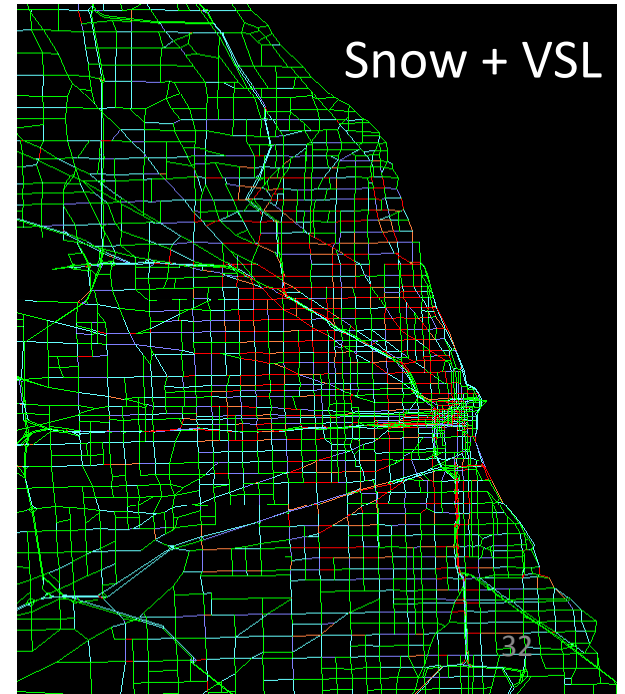
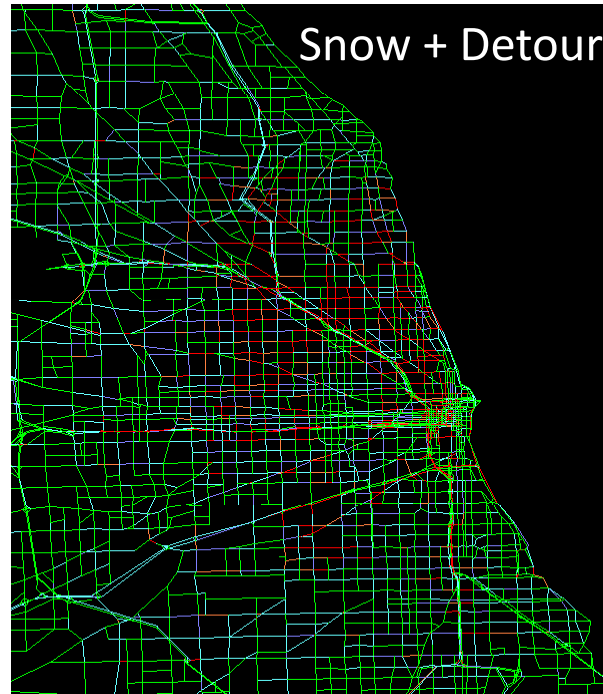
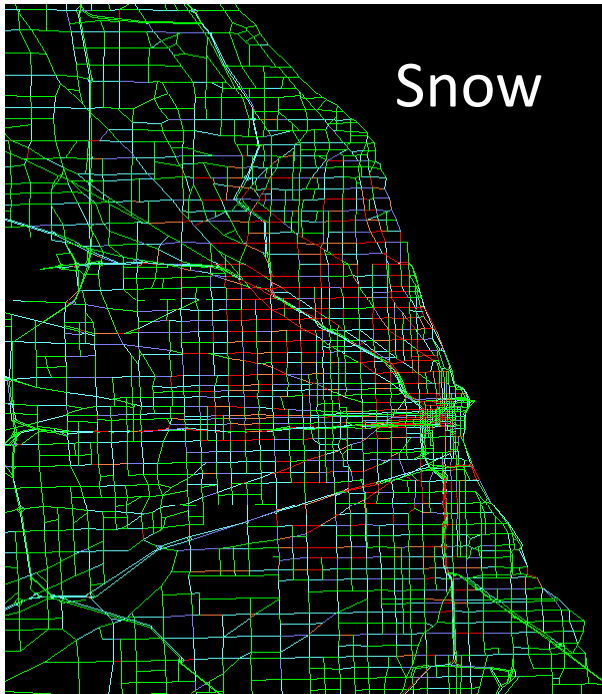
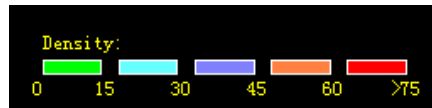
6:30 am  
Density



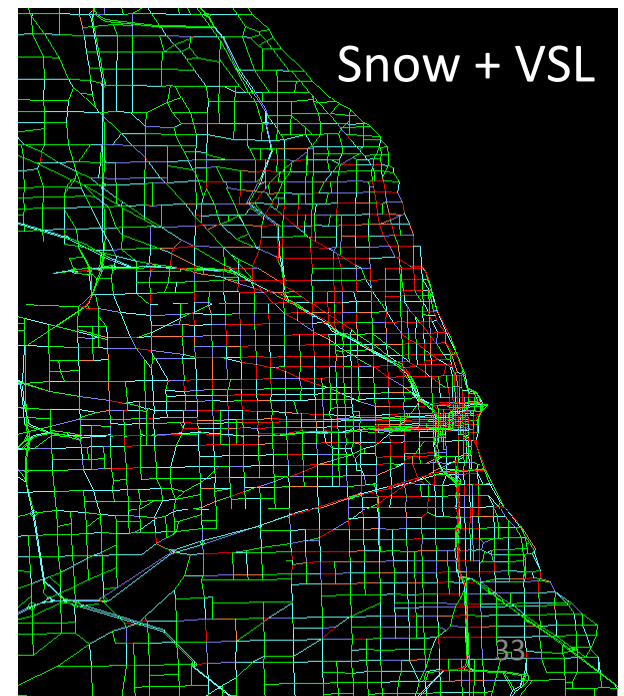
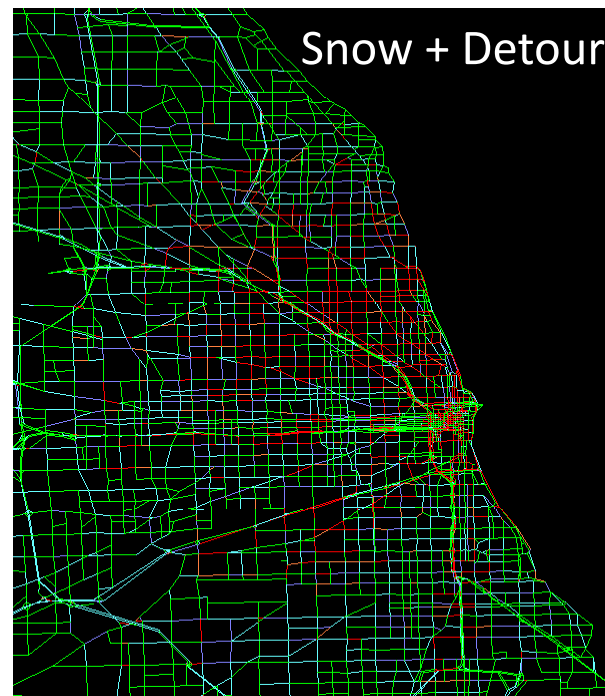
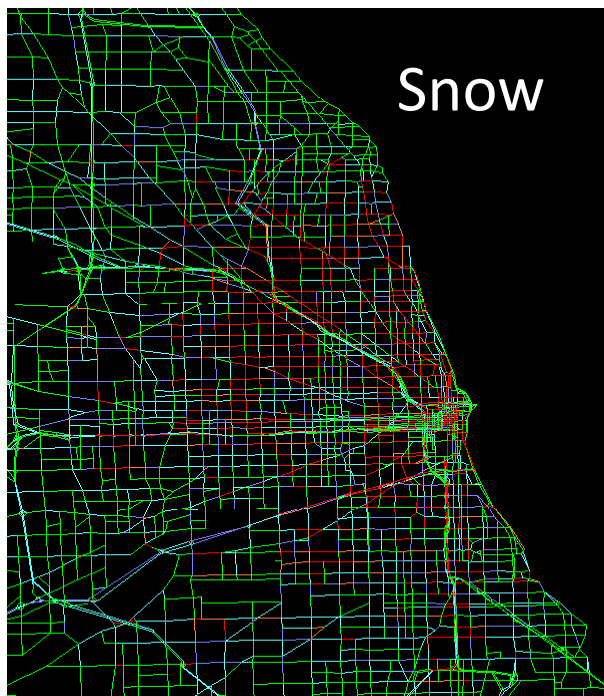
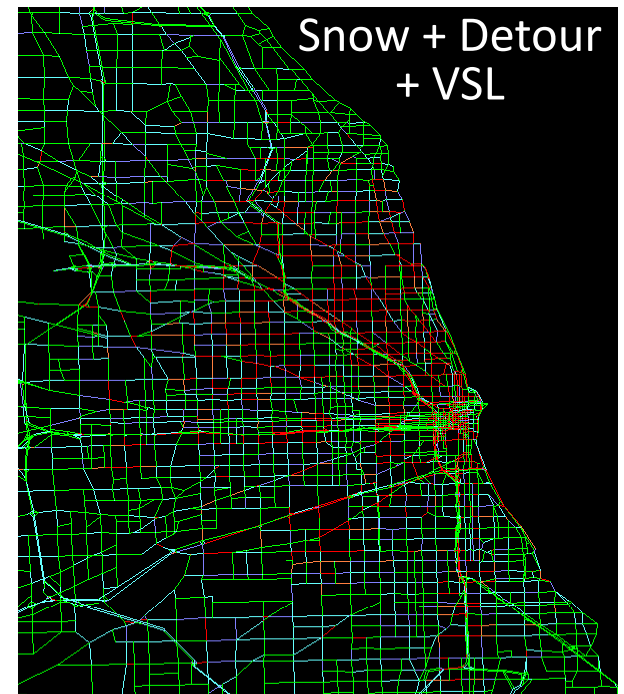
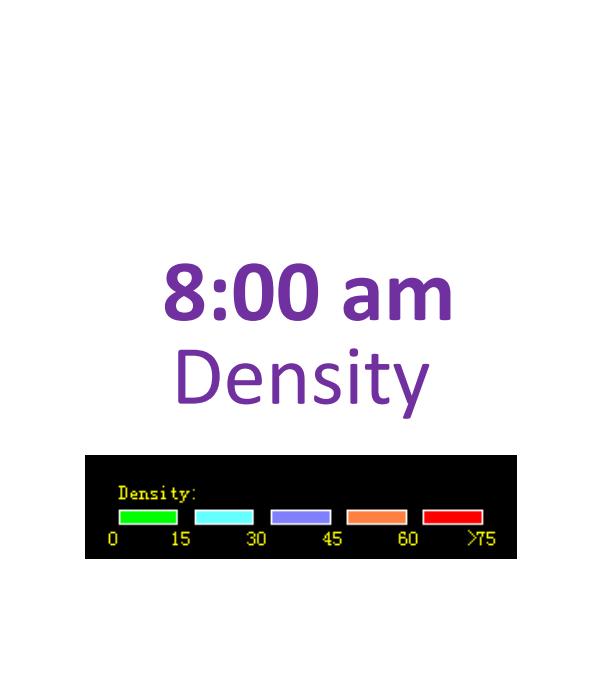
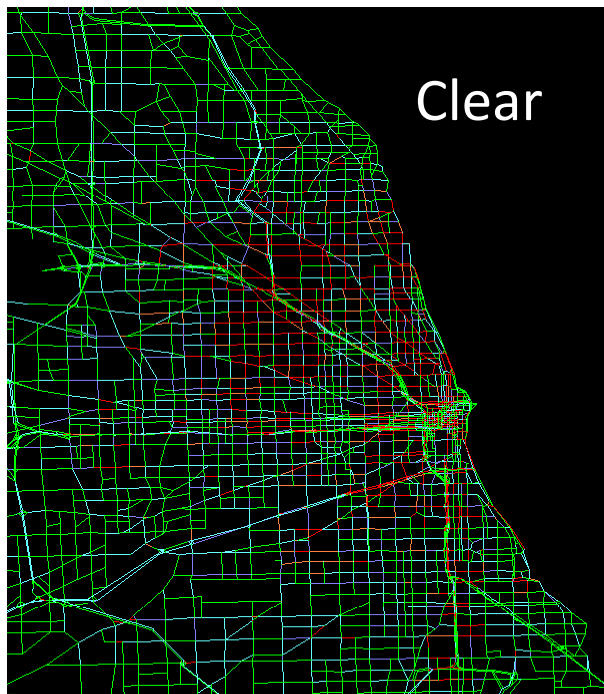


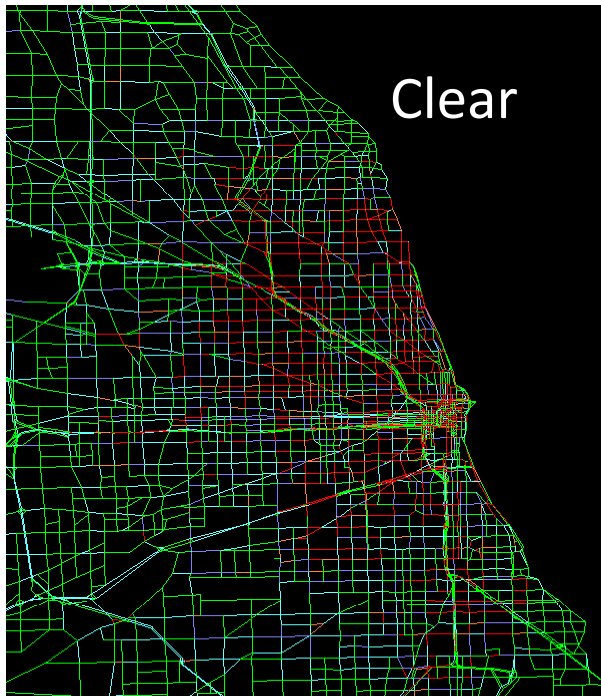


7:30 am  
Density

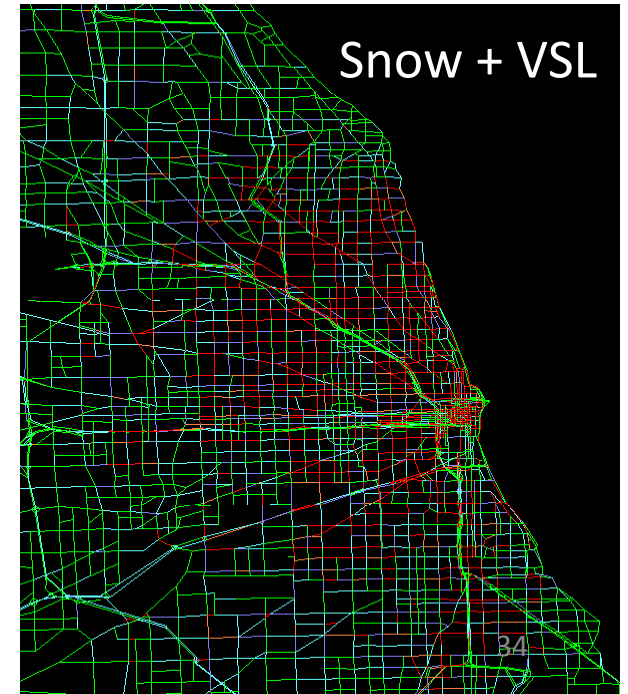
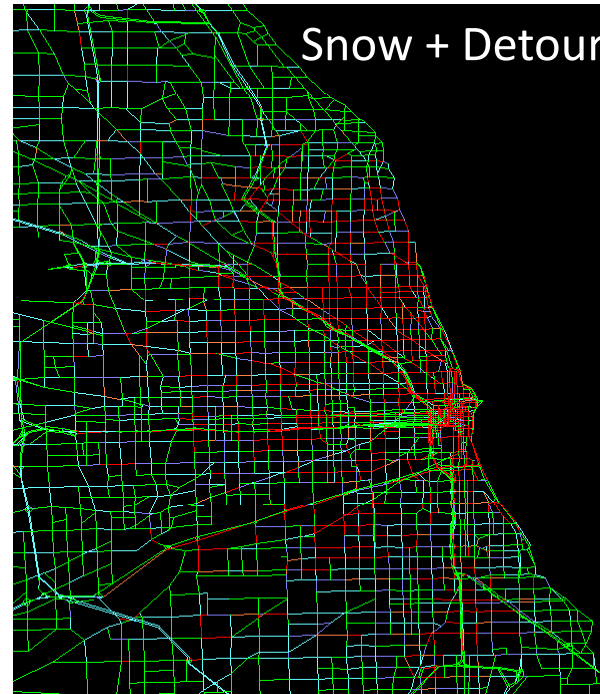
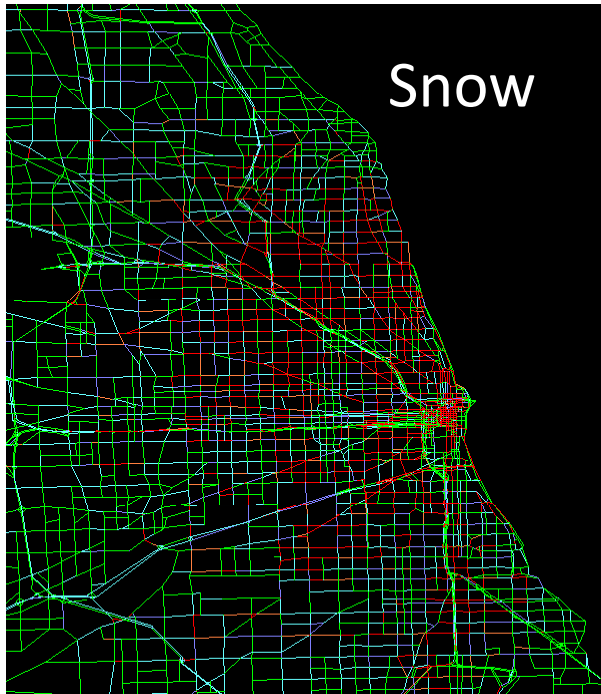
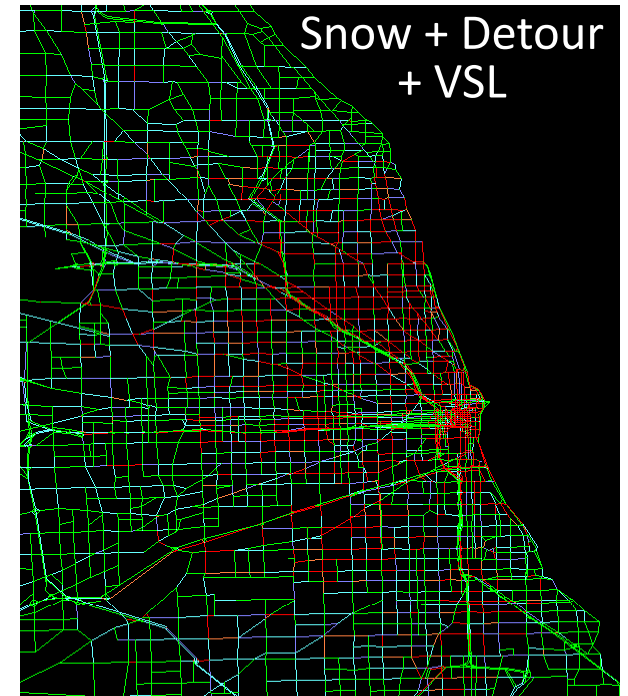
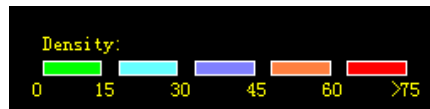


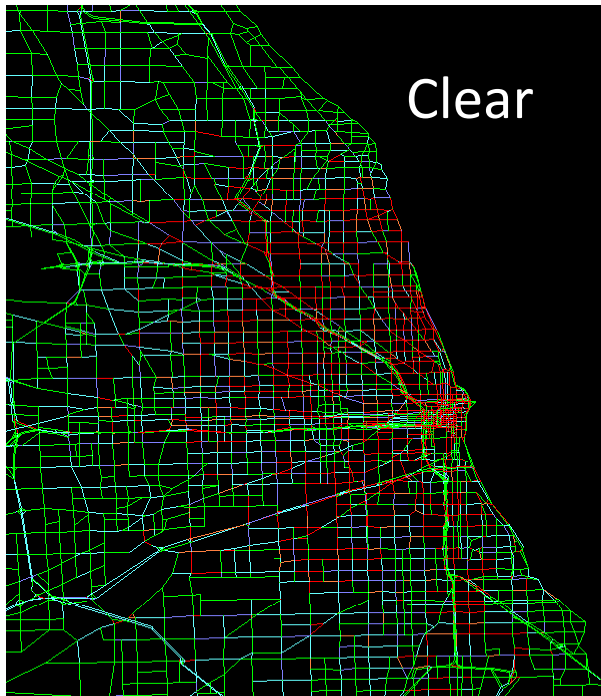




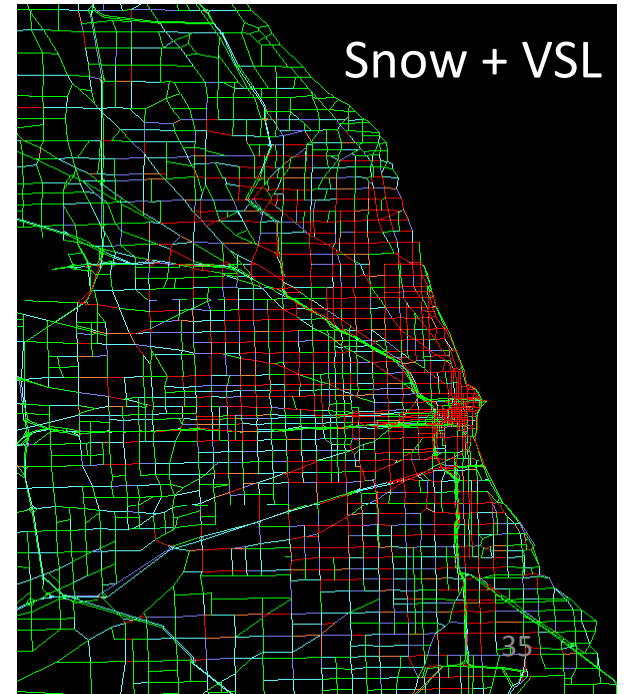
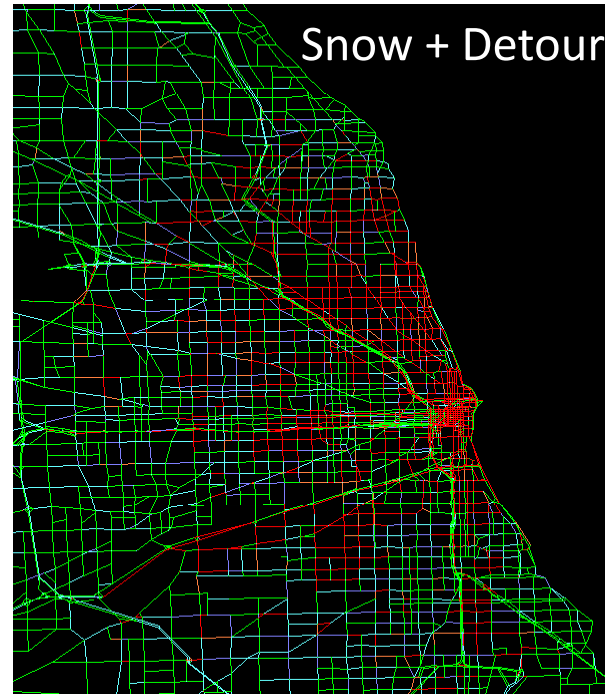
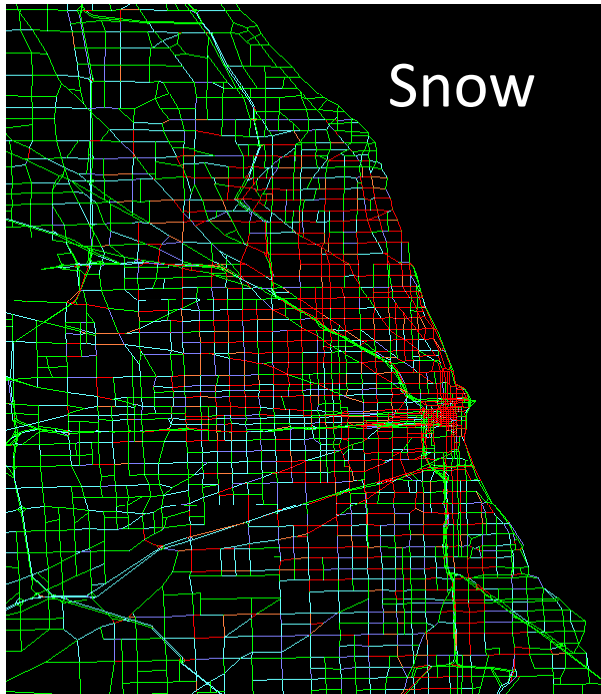
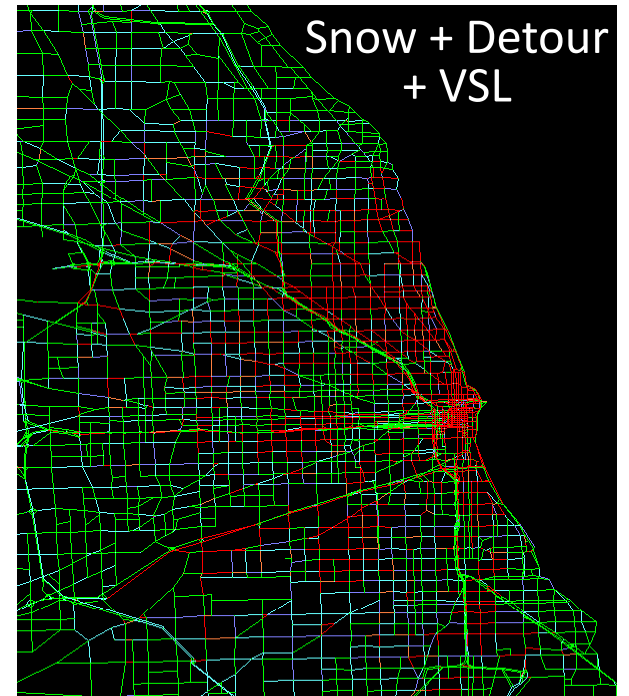
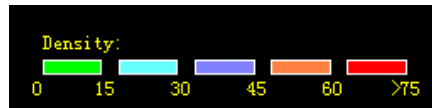


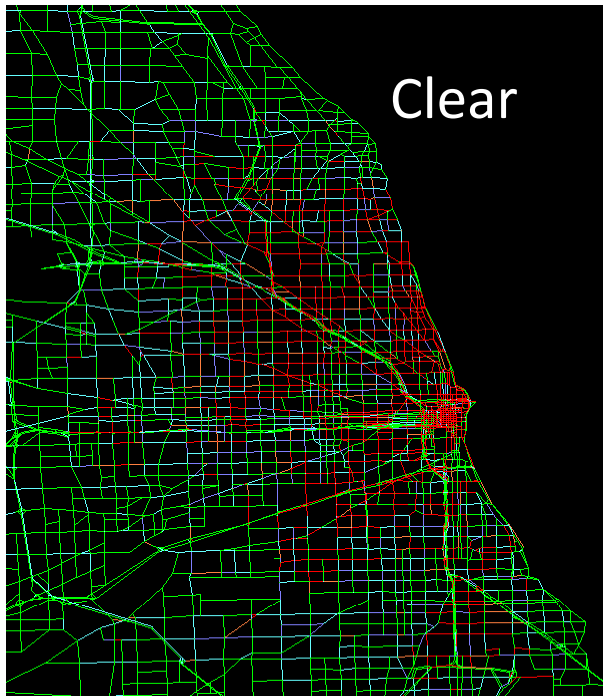
8:30 am  
Density



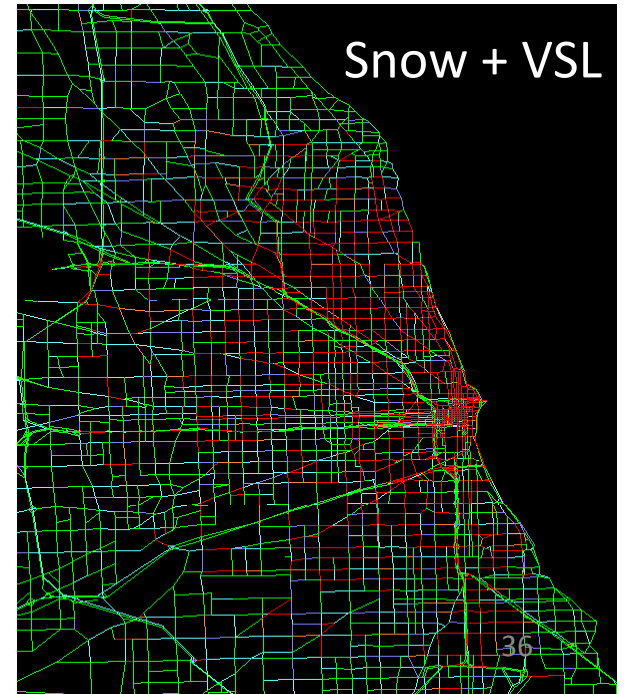
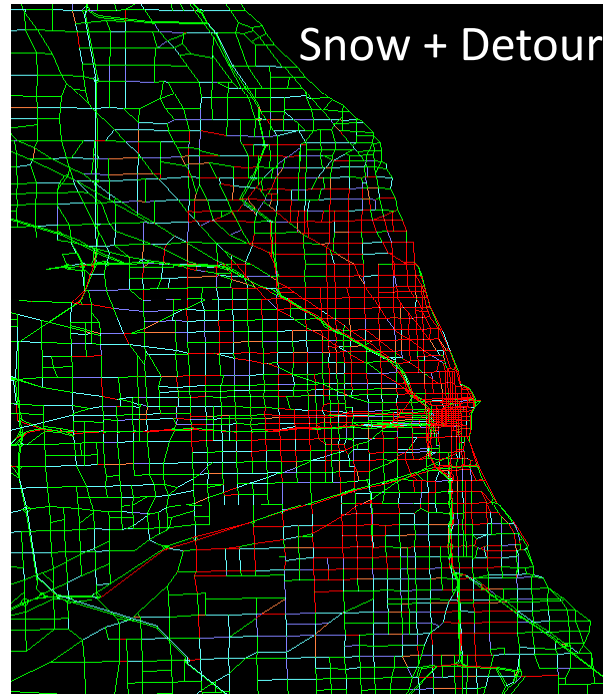
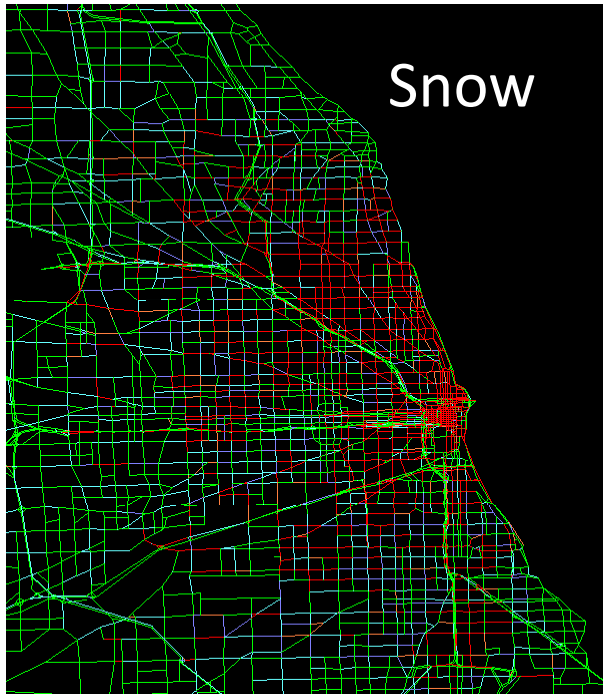
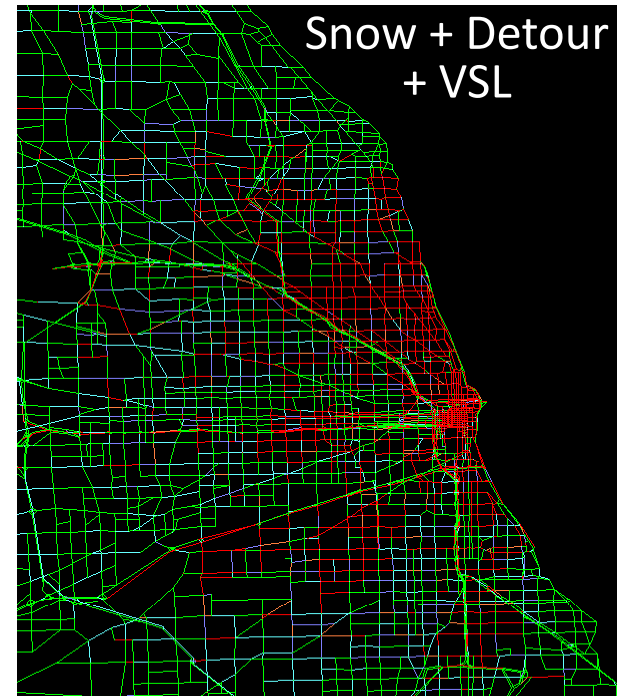
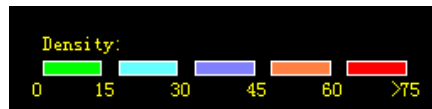


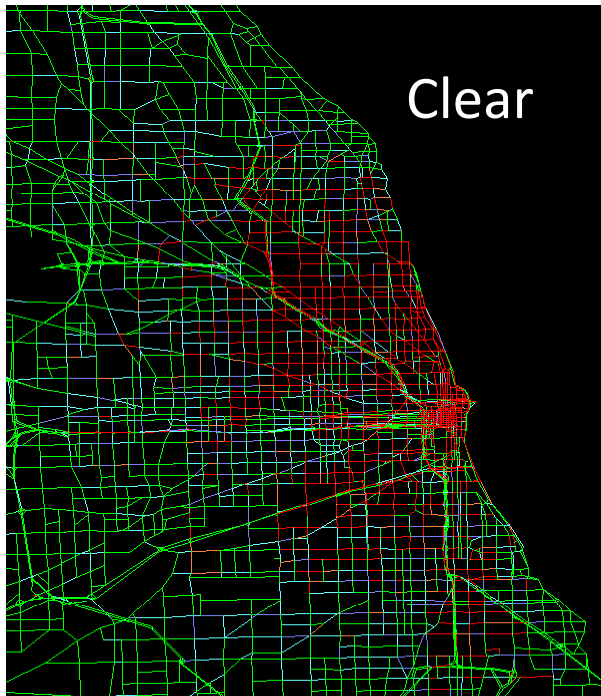
9:00 am  
Density



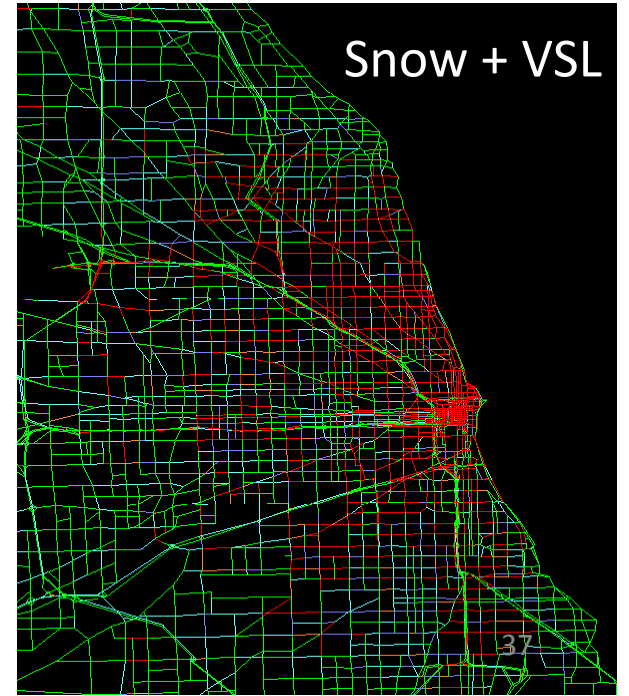
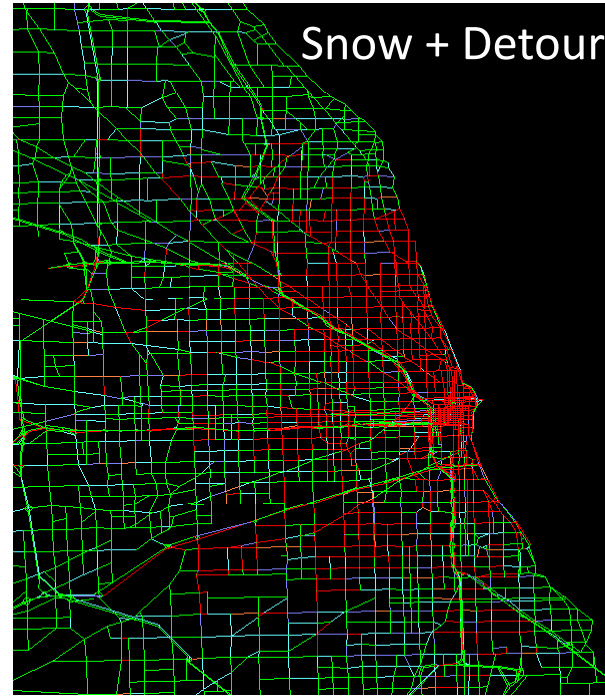
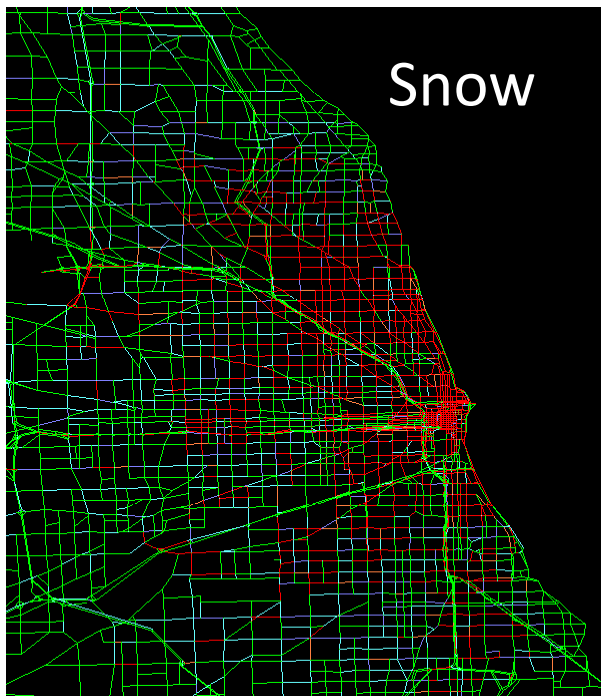
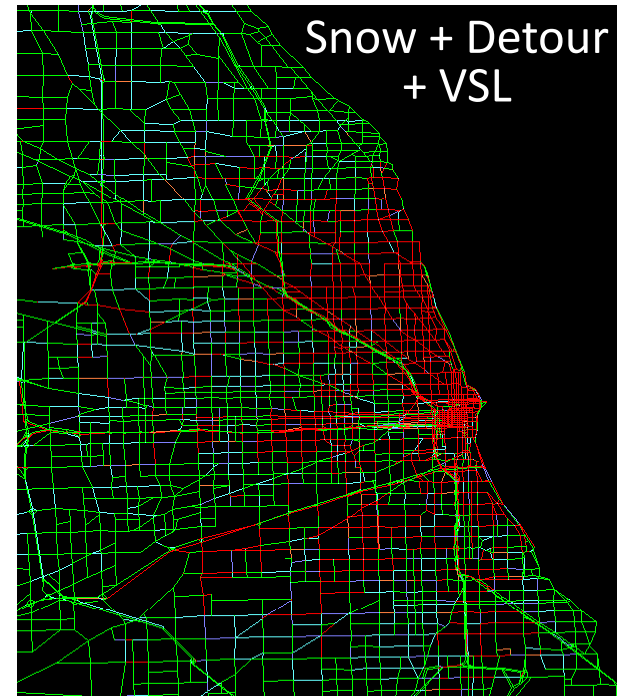
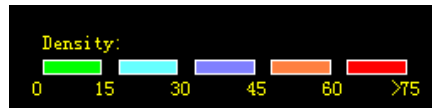


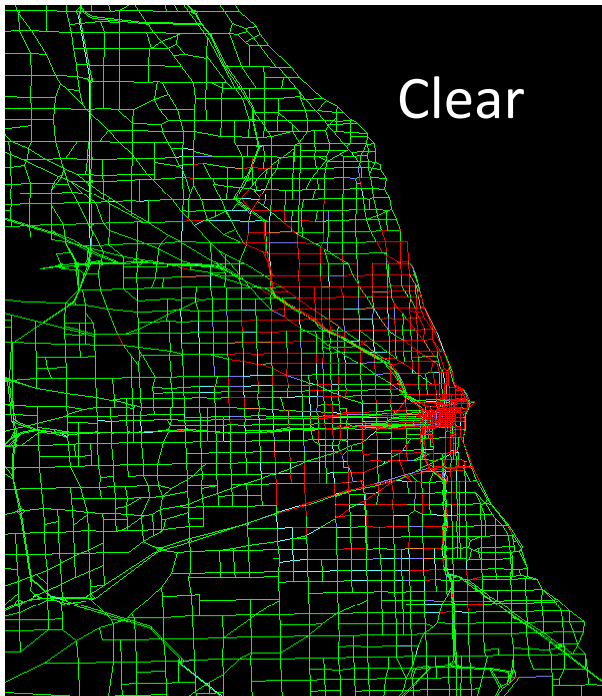
9:30 am  
Density



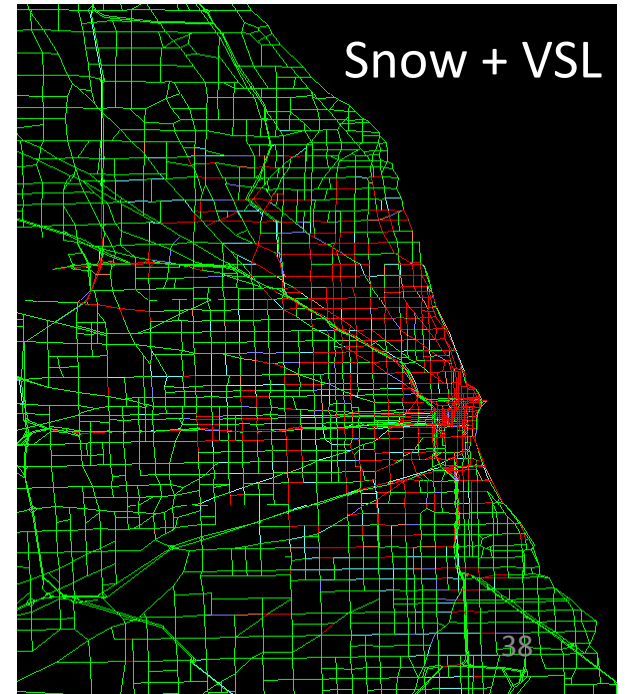
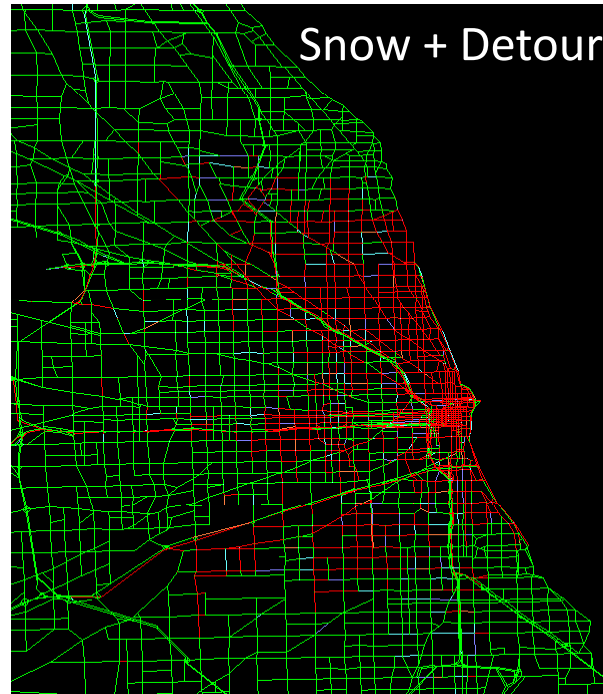
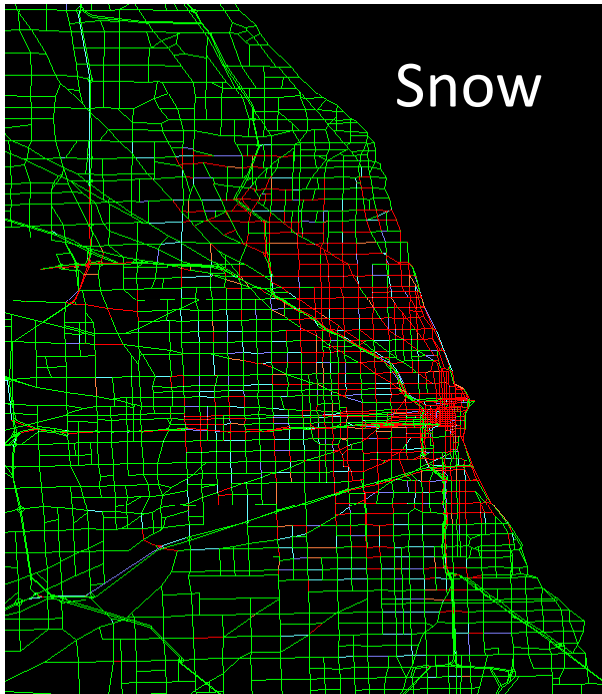
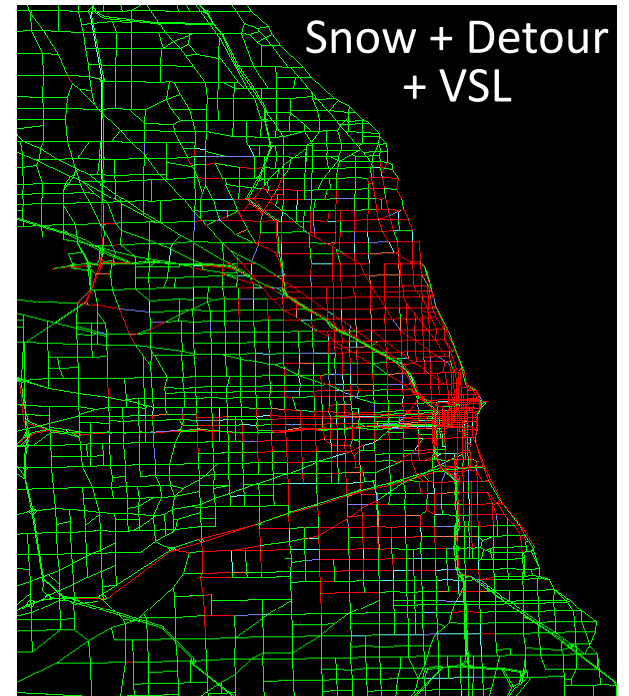
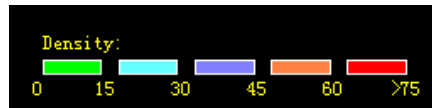


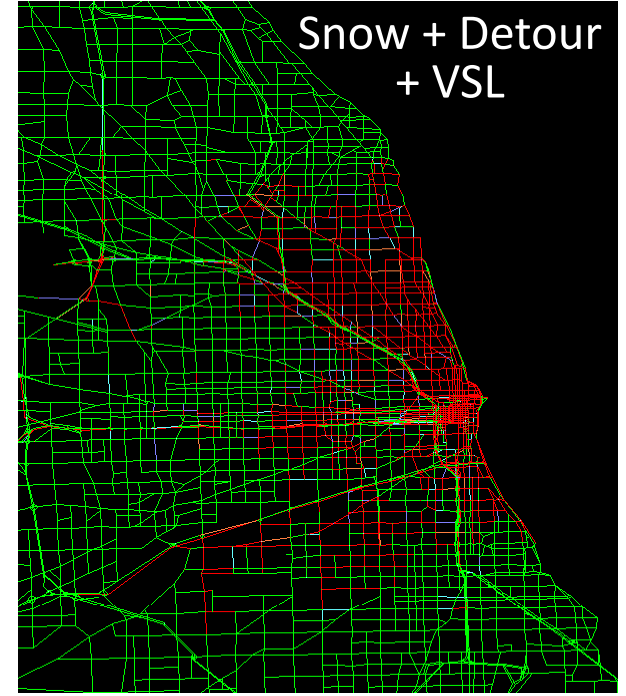
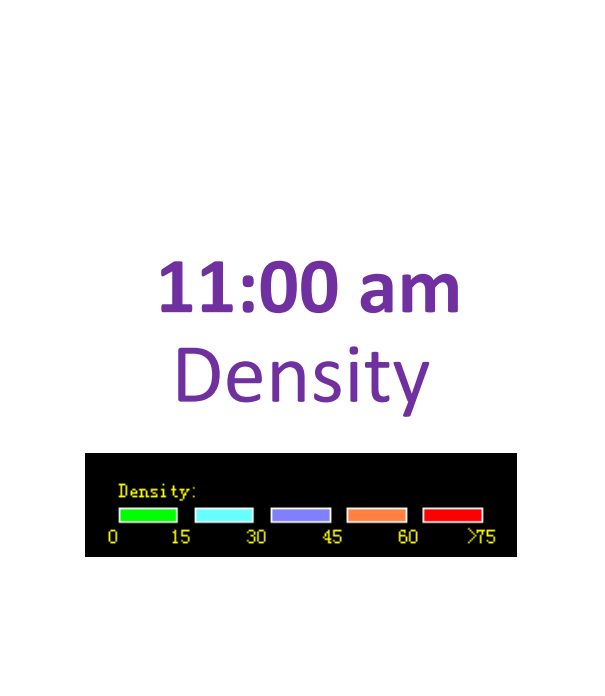
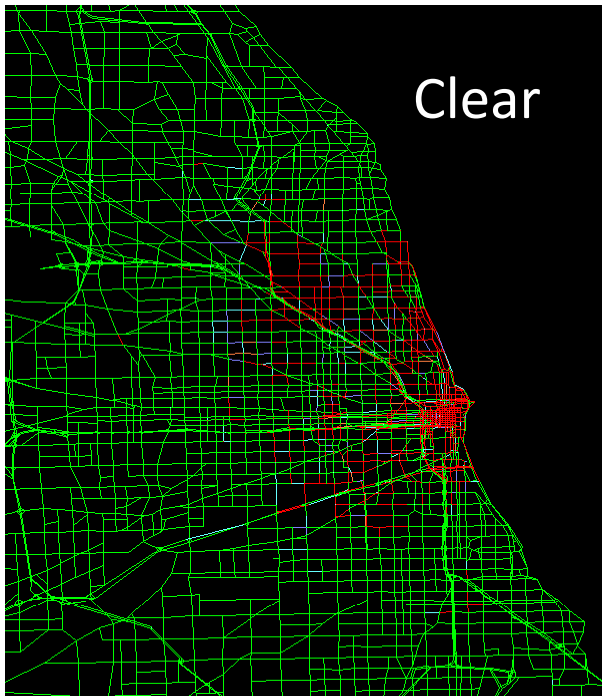
10:00 am  
Density



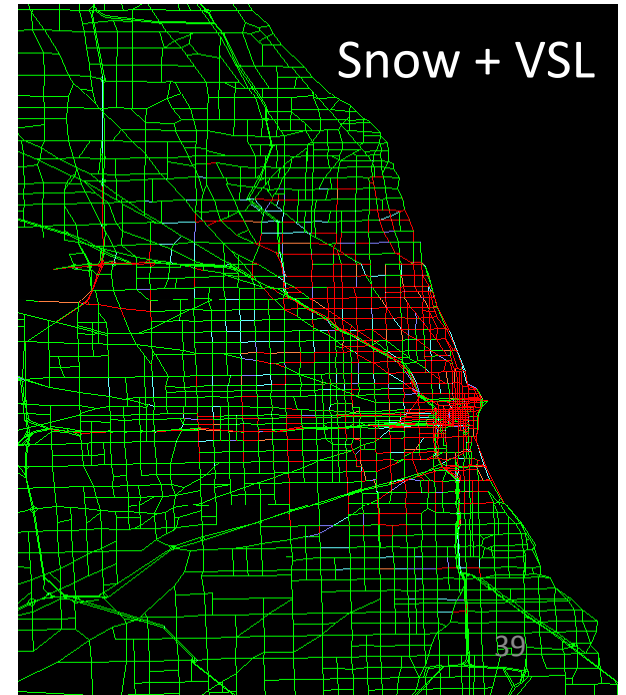
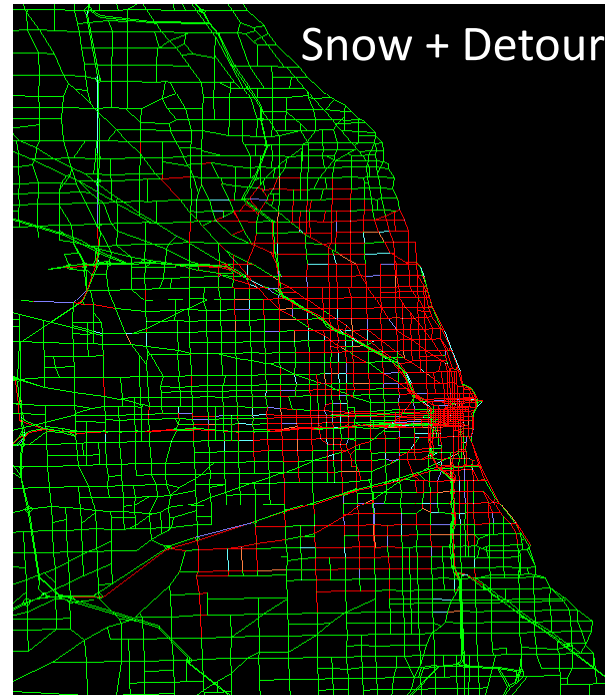
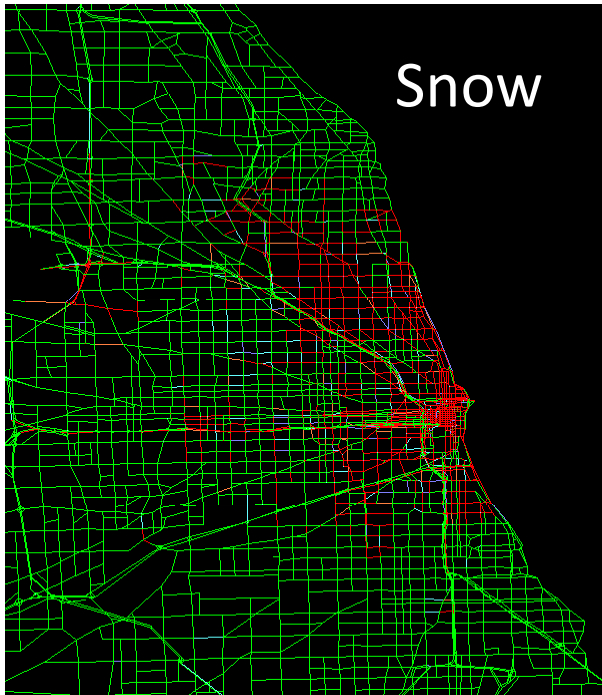
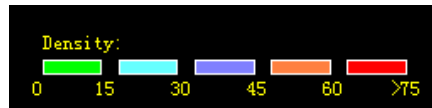


10:30 am  
Density

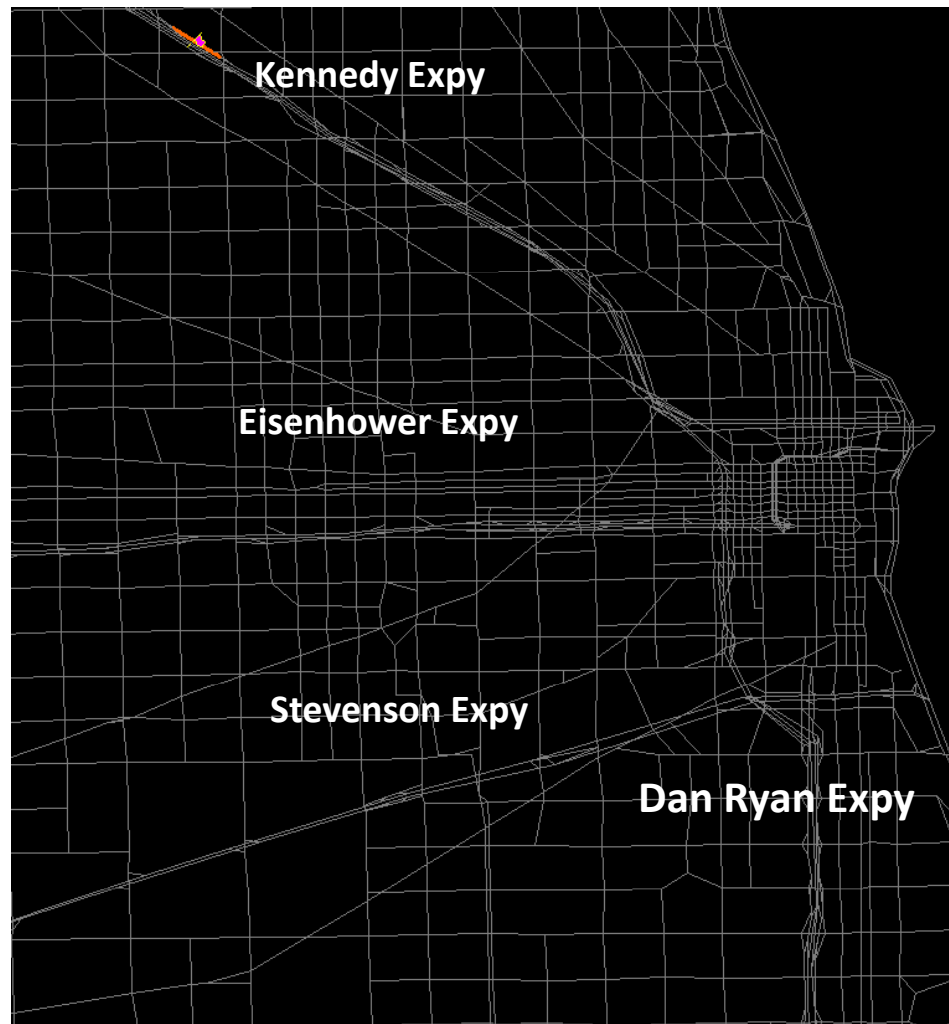




11:00 am  
Density

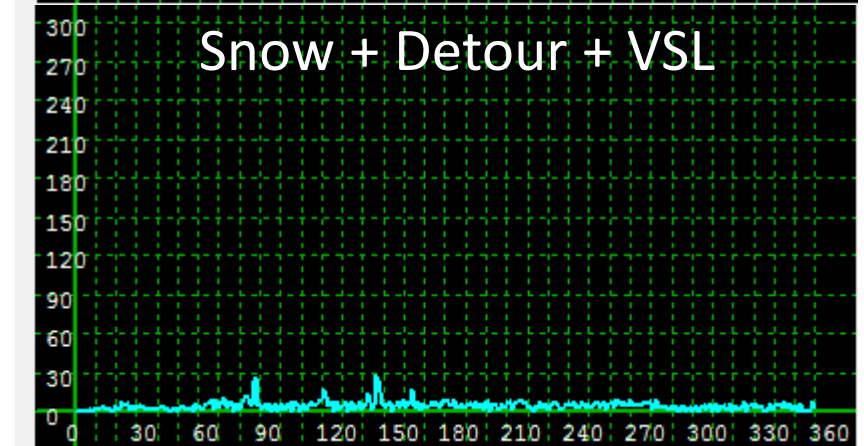
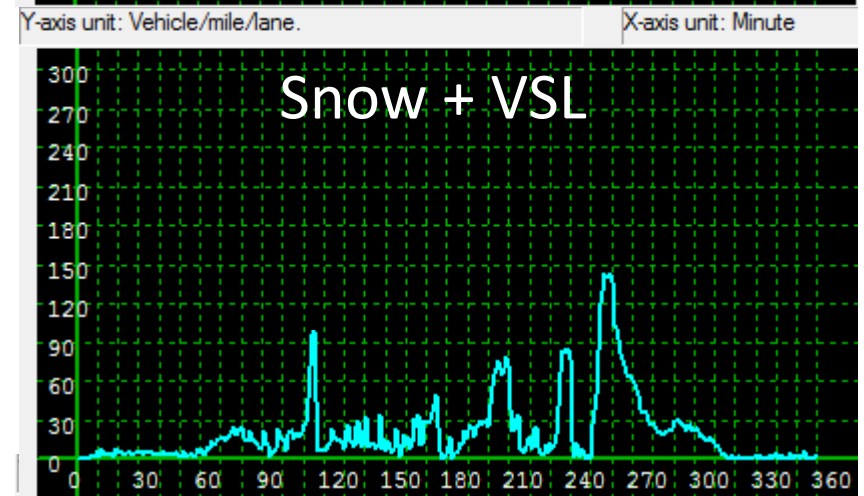
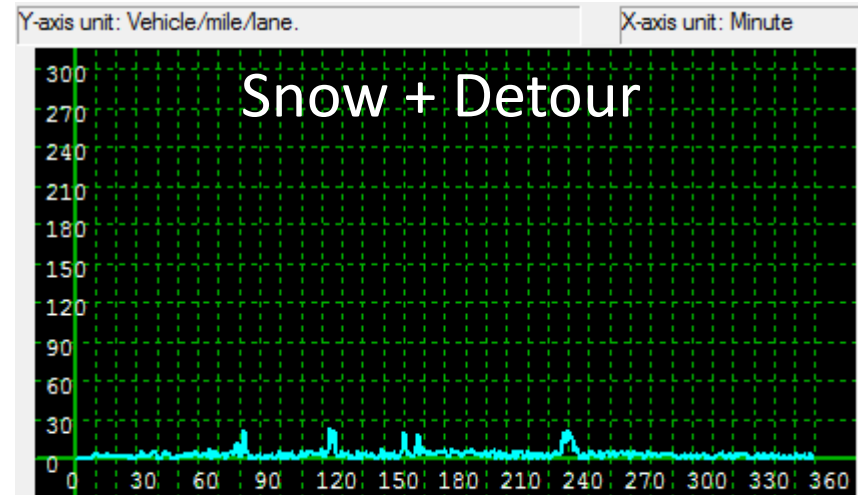
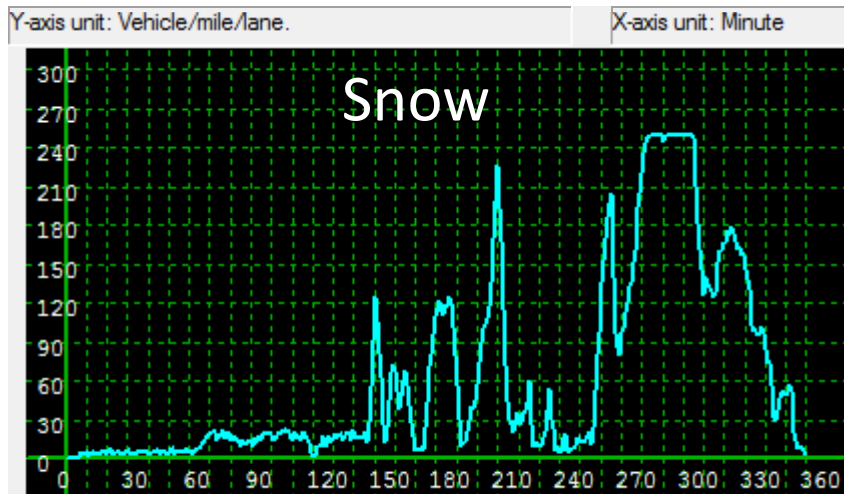
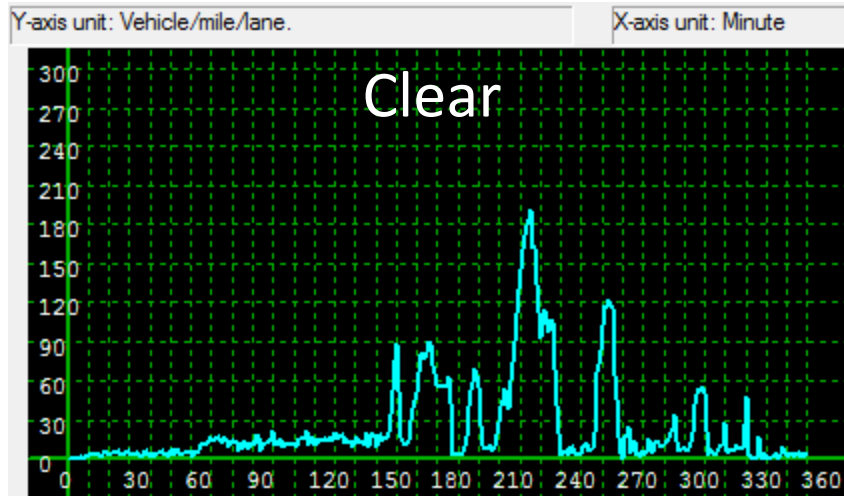


# A Closer Look: Link Densities and Speeds

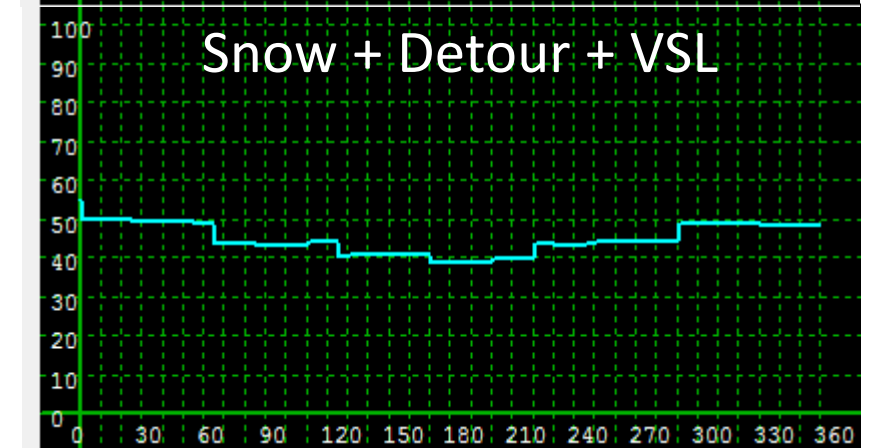
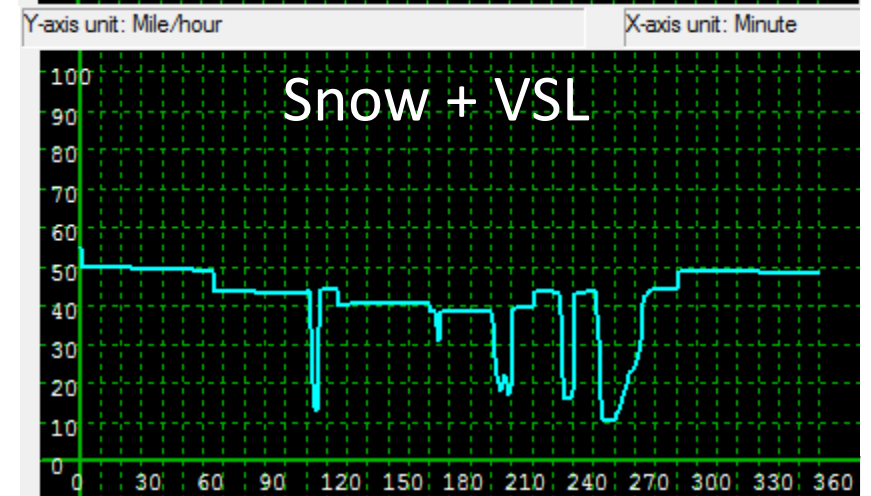
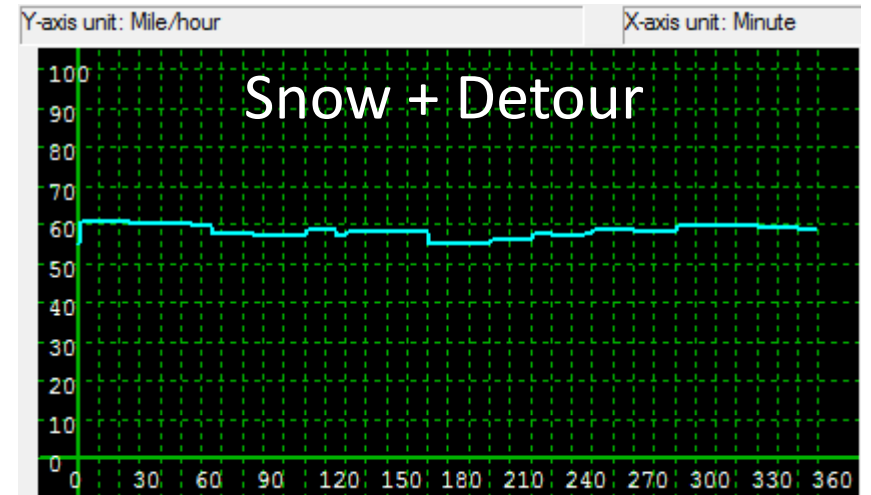
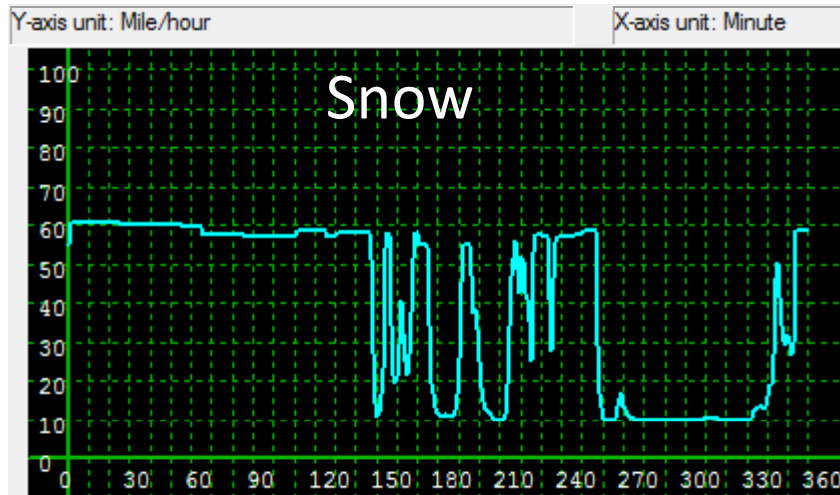
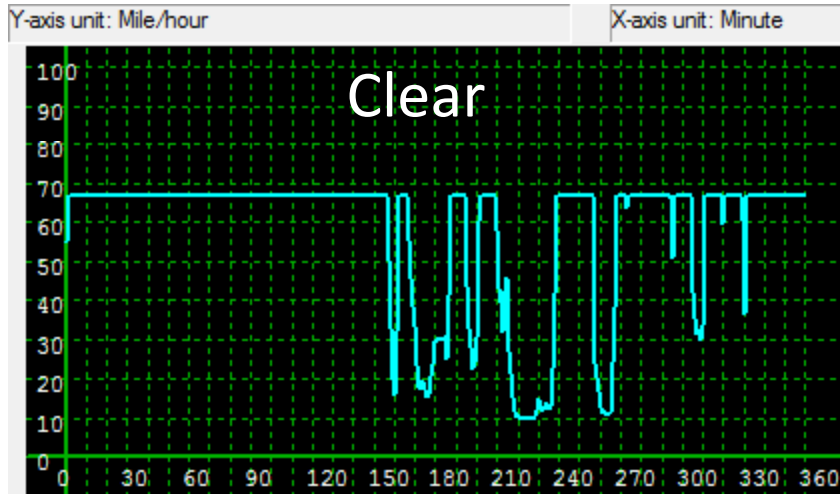




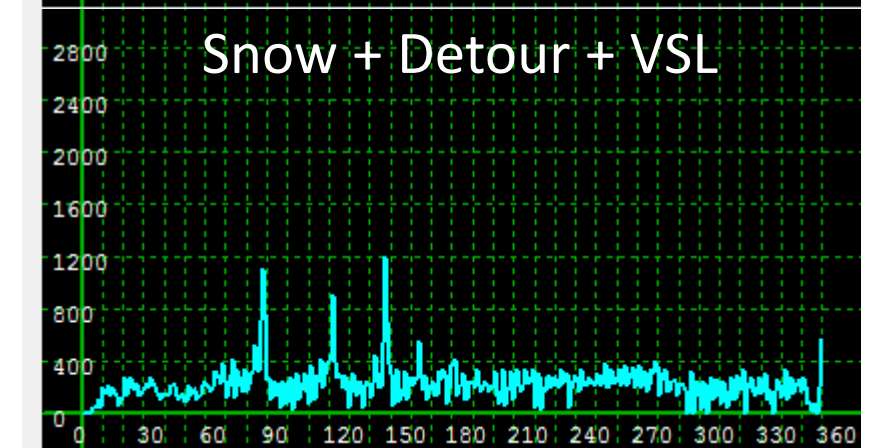
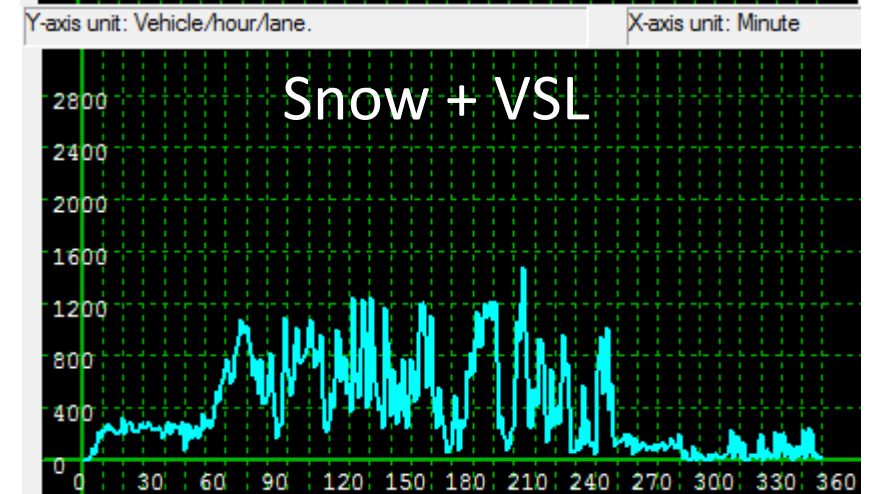
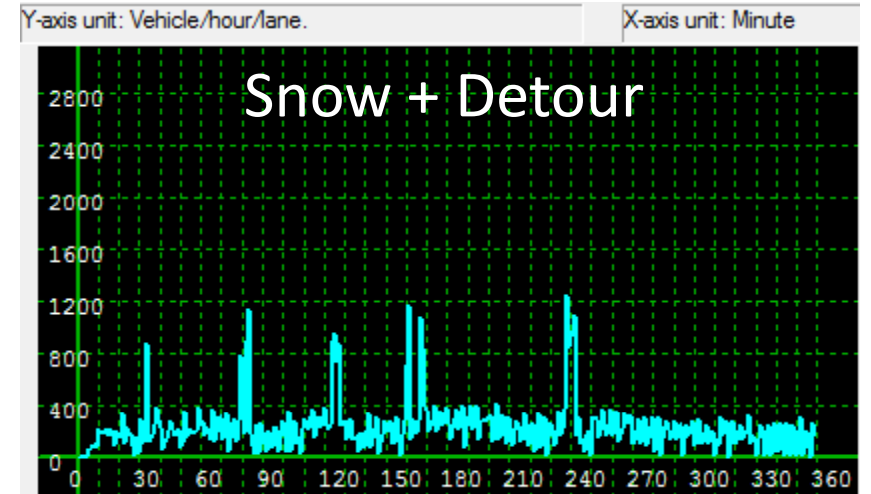
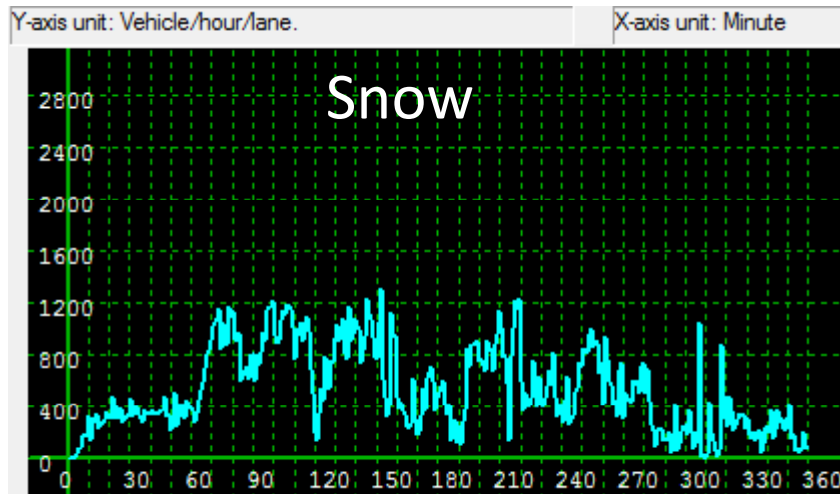
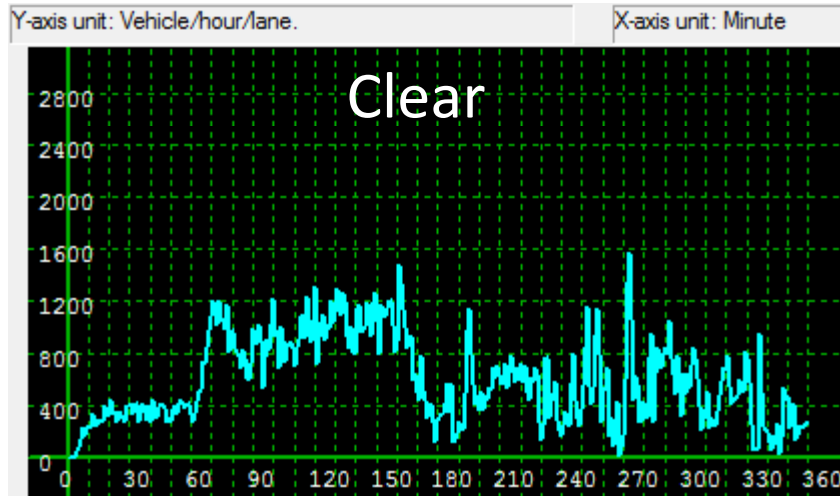
# Kennedy Expy between Pulaski Rd and N Cicero Ave (west bound) (Density)



# Kennedy Expy between Pulaski Rd and N Cicero Ave (west bound) (Speed)



# Kennedy Expy between Pulaski Rd and N Cicero Ave (west bound) (Volume)



## Application I- Weather-responsive traffic estimation and prediction

- A **validated offline WRTM** strategy can provide a predefined input to be used for **online WRTM**.
- **Variable Speed Limit (VSL)** is a more general strategy which can be implemented for an entire corridor and can be **evaluated offline**.
- **Detour (VMS2)** is a strategy that should always be considered. However, its effectiveness should not be tested offline as it is more **case-dependent**.
- This calls the **need** for an **online implementation** with **Detector Measurement data** and **Weather Prediction** in order to predict near-future events based on prevailing real-world conditions and make **proper interventions** using **online WRTM** strategies.

# Applications

## II- Congestion management

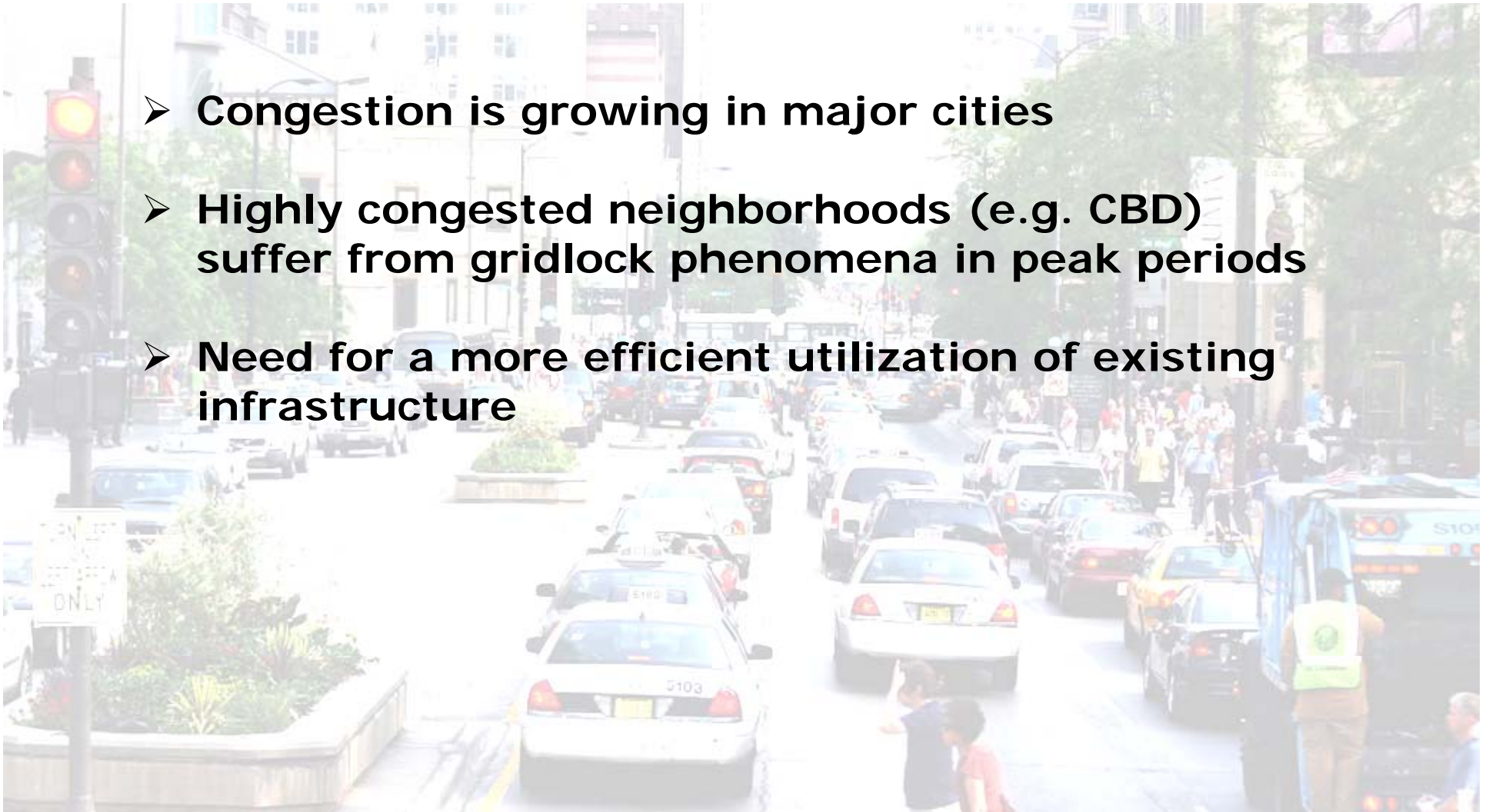
## Application II- Congestion management

# What is the Problem?



# What is the Problem?

- Congestion is growing in major cities
- Highly congested neighborhoods (e.g. CBD) suffer from gridlock phenomena in peak periods
- Need for a more efficient utilization of existing infrastructure



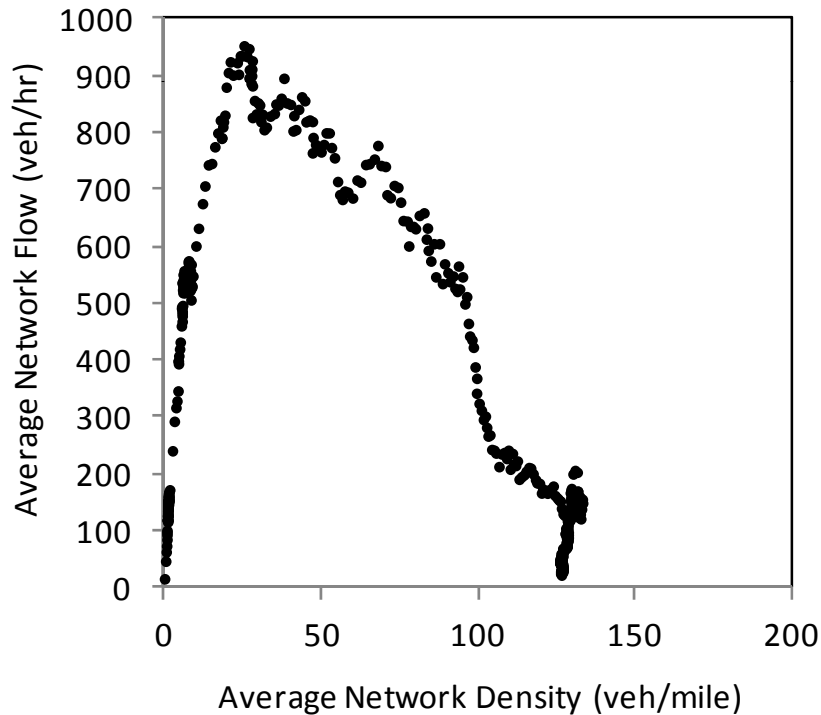
# Objectives

- **Improve mobility and accessibility**
- **Congestion mitigation**
- **Finding an effective and practical solution**





# City-wide Traffic Flow Relations



## Traffic Control

Network Flow

Network Speed

Network Density

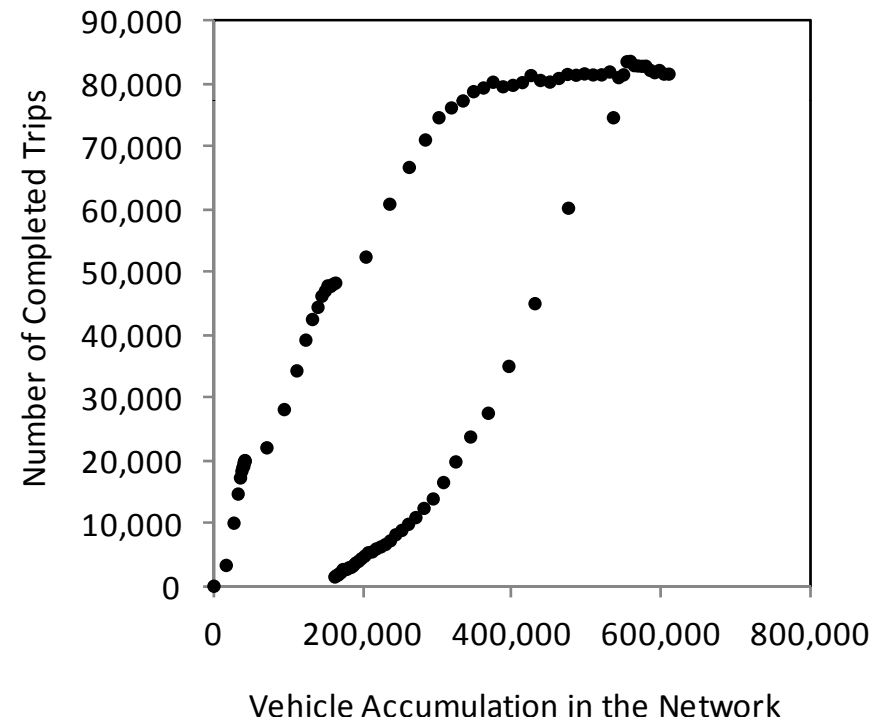
# City-wide Traffic Flow Relations

## Transportation Planning

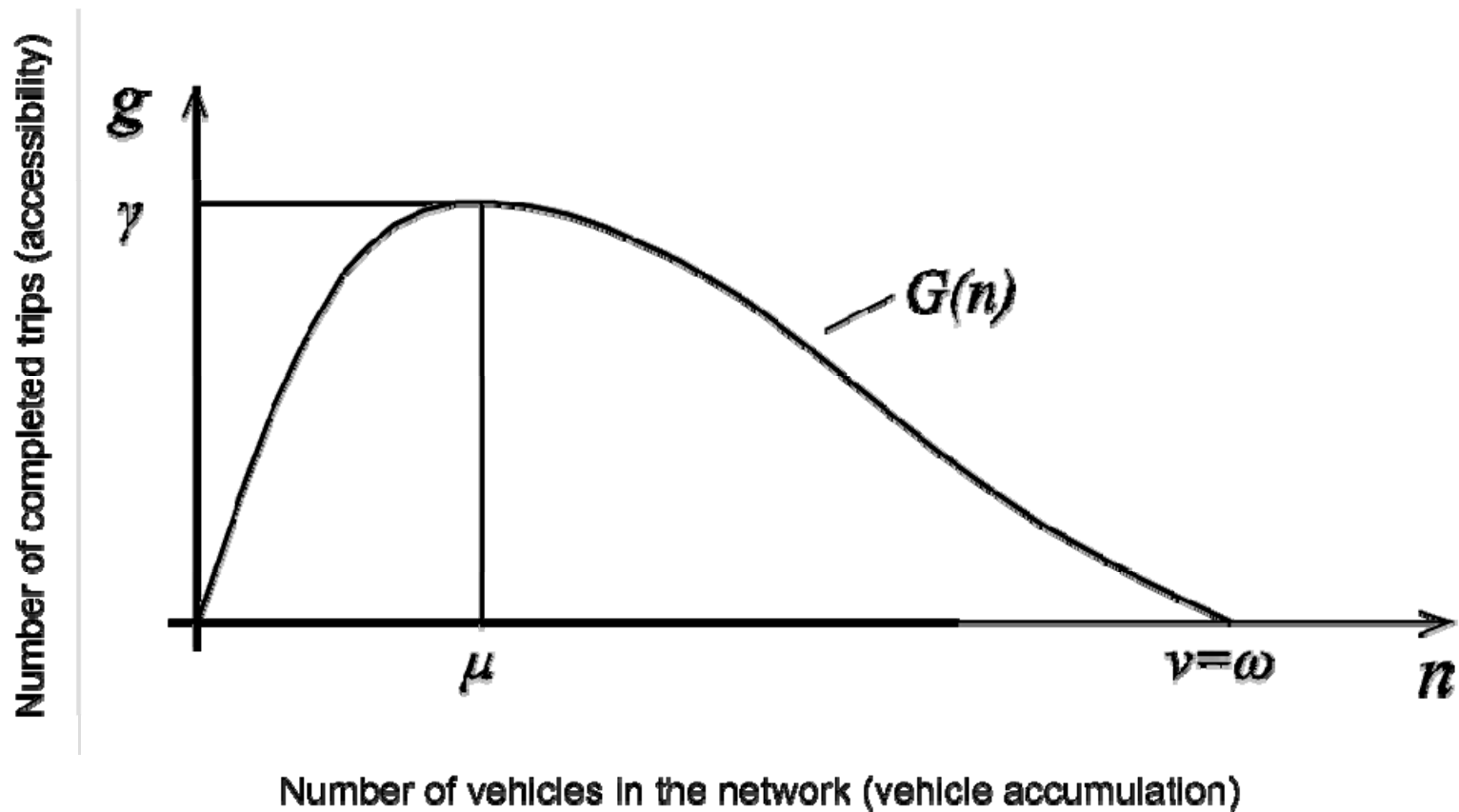
Mobility

Accessibility

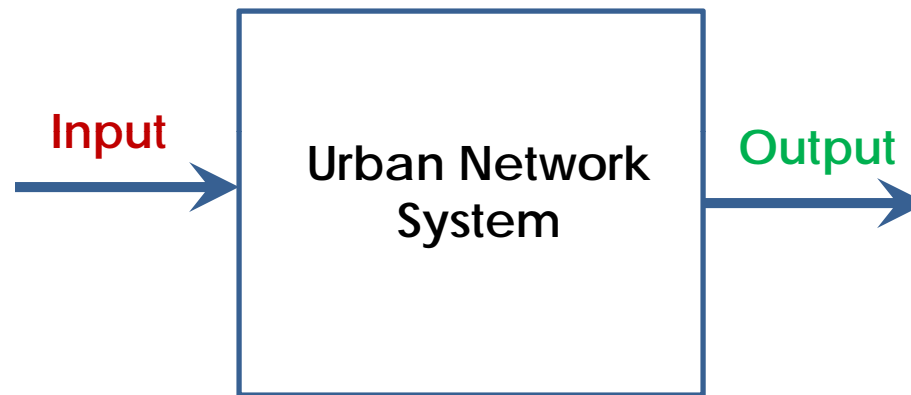
Vehicle Accumulation



# City-wide Traffic Flow Relations



## What is the idea?



The idea is to monitor and control aggregate **vehicle accumulation** in the network in order to maximize the **accessibility** and **mobility**.

# How can we do it?

London, UK



## Application II- Congestion management

# How can we do it?

Zurich, Switzerland



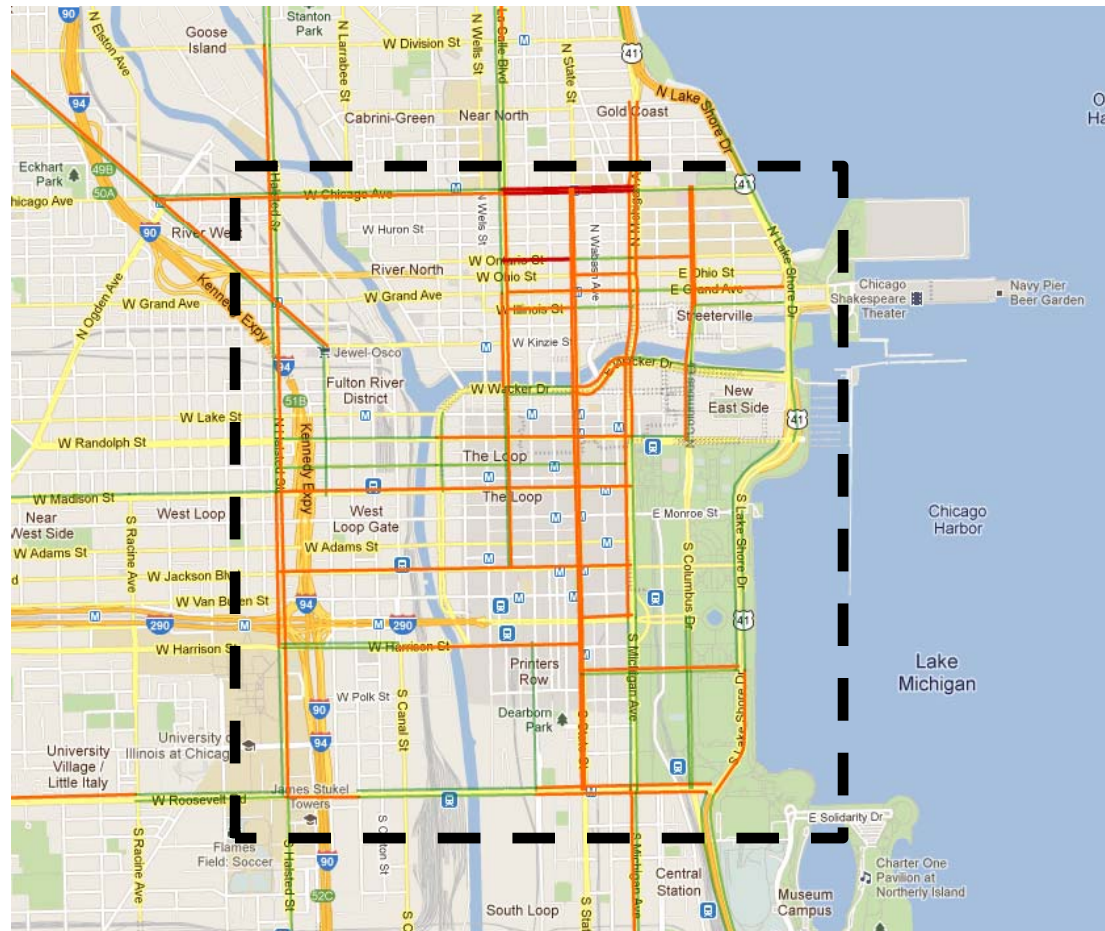
# How can we do it?

**Chicago, USA**



## Application II- Congestion management

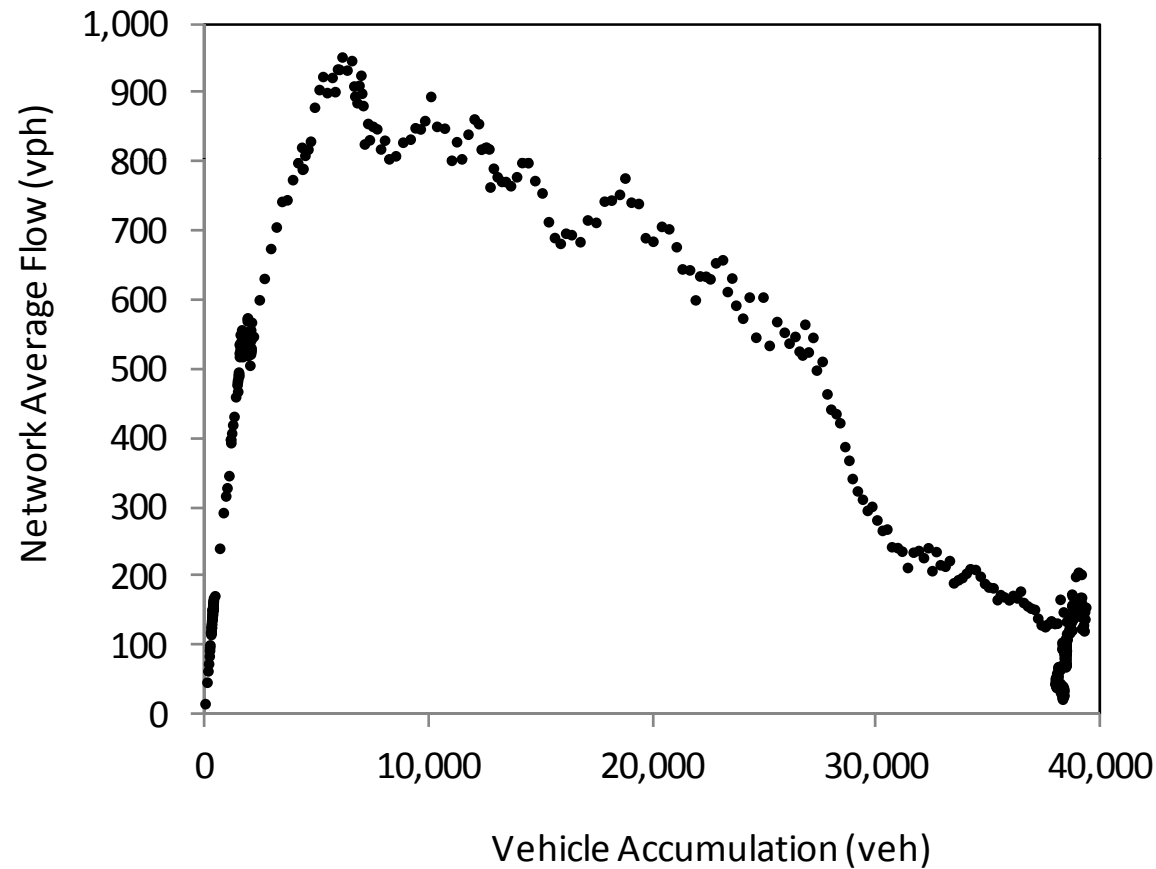
# Downtown Chicago





# Vehicle Accumulation vs. Network Flow

## Chicago CBD



# Gridlock formation

Gridlock (5% EnRoute)

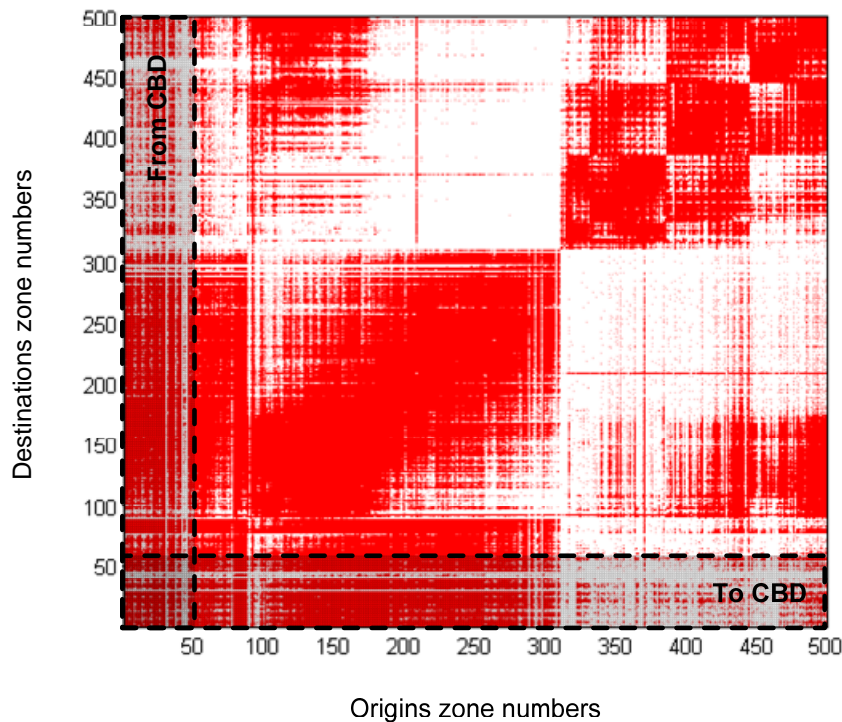


Gridlock (20% EnRoute)

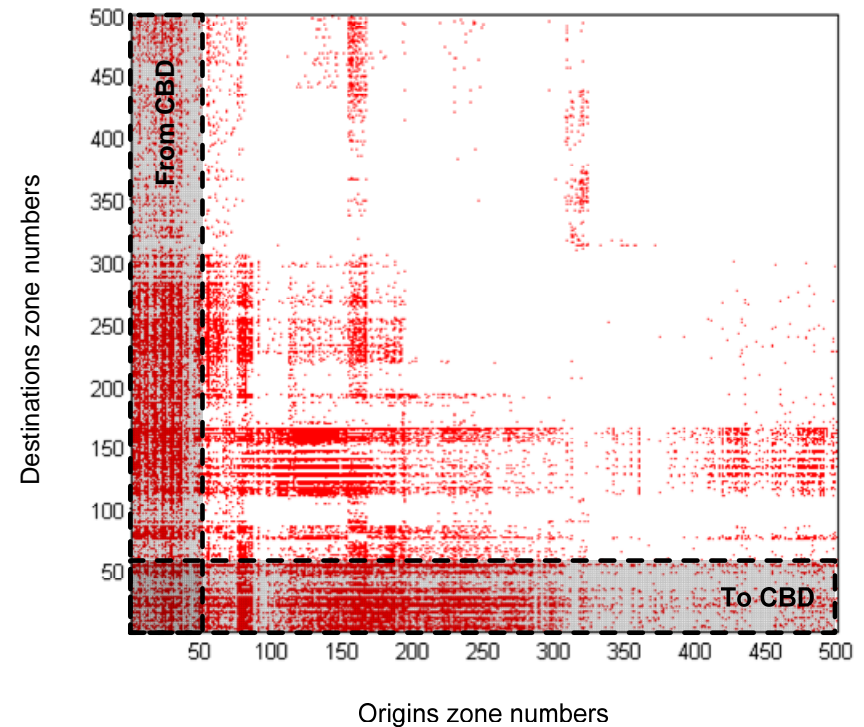


# Where they came from?

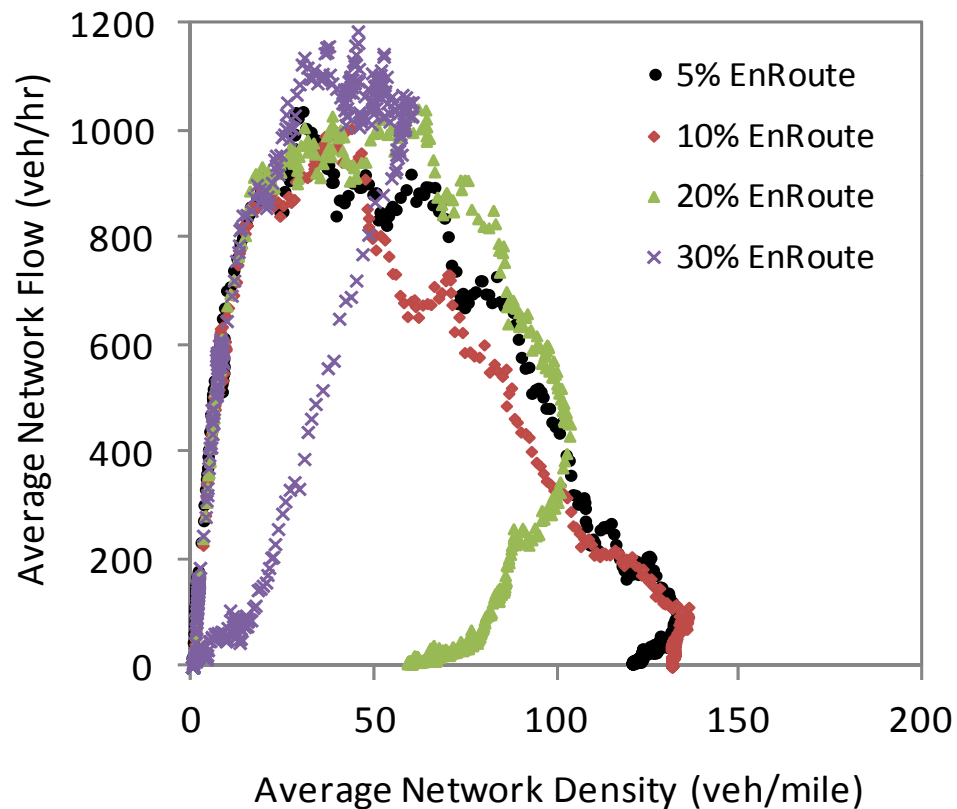
Spatial distribution of Origin-Destination demand in the network



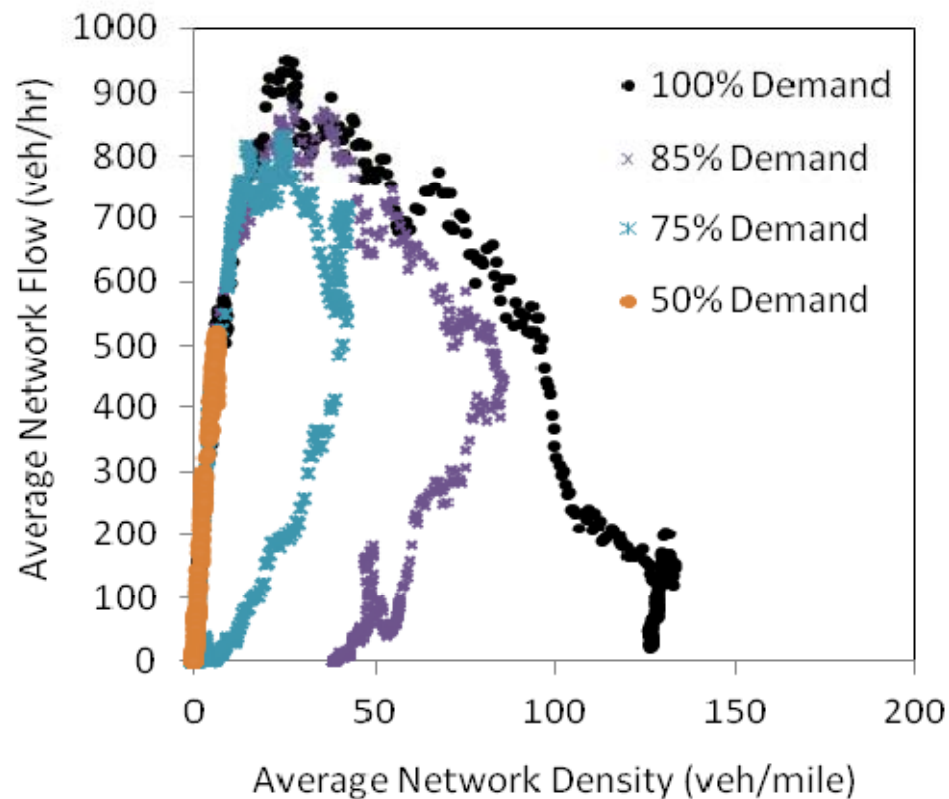
Spatial distribution of Origin-Destination demand associated with vehicles trapped in the gridlock



# Effect of traveler information



# Effect of demand management



# Work in progress

- We have identified 41 signals in the periphery of downtown Chicago.
- Restricting the accumulation of vehicles in downtown via modifying the **signal timings on the periphery** of downtown and/or pricing.
- Similar analysis will be performed in a **multi-modal network** to understand the impact of modes interaction and its effect on the network-wide mobility and accessibility.

# Summary

## Summary

- **Simulation-based DTA** tools overcome many of the known limitations of static assignment tools used in current practice.
- DYNASMART-P provides a platform for integrating **activity-based models** with network assignment and **performance simulation**.
- A Calibrated greater Chicago network is prepared in DYNASMART. Calibration includes both demand and supply side.
- Two Applications of DYNASMART-P were reviewed including :
  - **Weather-responsive** traffic estimation and prediction
  - Congestion management.



**Thank You**

**Questions ?**